

UNIT # 03

VECTOR CALCULUS

Introduction:

In this chapter, we shall discuss the vector functions, limits and continuity, differentiation and integration of a vector function.

Vector Function:

A vector function \vec{f} from set D to set R [$\vec{f} : D \rightarrow R$] is a rule or correspondence that assigns to each

Element t in set D exactly one element y in set R . It is written as $y = \vec{f}(t)$.

For your information (i) Set D is called domain of \vec{f} . (ii) Set R is called range of \vec{f} .

Limit of Vector Function:

A constant L is called Limit of vector function $\vec{f}(t)$ by taken t approaches to a ($t \neq a$).

It is written as $\lim_{t \rightarrow a} \vec{f}(t) = L$ [It is studied as $\vec{f}(t) \rightarrow L$ as $t \rightarrow a$]

Rules of Limit:

(1) $\lim_{t \rightarrow a} [k \cdot \vec{f}(t)] = k \cdot \lim_{t \rightarrow a} \vec{f}(t)$ (k is any scalar number)

(2) $\lim_{t \rightarrow a} [\vec{f}(t) \pm \vec{g}(t)] = [\lim_{t \rightarrow a} \vec{f}(t)] \pm [\lim_{t \rightarrow a} \vec{g}(t)]$

(3) $\lim_{t \rightarrow a} [\vec{f}(t) \times \vec{g}(t)] = [\lim_{t \rightarrow a} \vec{f}(t)] \times [\lim_{t \rightarrow a} \vec{g}(t)]$

(4) $\lim_{t \rightarrow a} \left[\frac{\vec{f}(t)}{\vec{g}(t)} \right] = \frac{[\lim_{t \rightarrow a} \vec{f}(t)]}{[\lim_{t \rightarrow a} \vec{g}(t)]}$

(5) $\lim_{t \rightarrow a} [\vec{f}(t)]^n = [\lim_{t \rightarrow a} \vec{f}(t)]^n$

Continuity of a Vector Function:

Let $\vec{f}(t)$ is a vector function. It is called continuous at $t = a$. If $\lim_{t \rightarrow a} \vec{f}(t) = \vec{f}(a)$.

Otherwise we say that $\vec{f}(t)$ is discontinuous.

Differentiation of a Vector Function:

Let $\vec{r} = \vec{f}(t)$ be a vector function. Then

$$\vec{f}'(t) = \lim_{\delta t \rightarrow 0} \frac{\vec{f}(t+\delta t) - \vec{f}(t)}{\delta t} \quad \text{or} \quad \frac{d\vec{r}}{dt} = \lim_{\delta t \rightarrow 0} \frac{\delta \vec{r}}{\delta t}$$

Is called Differentiation of a vector function. It also called 1st derivative .

Its 2nd , 3rd and so on nth-order derivative are written as

$$\begin{array}{ccc} \vec{f}''(t) & \text{or} & \frac{d^2\vec{r}}{dt^2} \\ \vec{f}'''(t) & \text{or} & \frac{d^3\vec{r}}{dt^3} \\ : & & : \\ : & & : \\ \vec{f}^n(t) & \text{or} & \frac{d^n\vec{r}}{dt^n} \end{array}$$

Example#02: If $\vec{r}(t) = \sin t \hat{i} + \cos t \hat{j} + t \hat{k}$. Find (i) $\frac{d\vec{r}}{dt}$ (ii) $\frac{d^2\vec{r}}{dt^2}$ (iii) $\left| \frac{d\vec{r}}{dt} \right|$ (iv) $\left| \frac{d^2\vec{r}}{dt^2} \right|$

Solution: Given $\vec{r}(t) = \sin t \hat{i} + \cos t \hat{j} + t \hat{k}$

(i) $\frac{d\vec{r}}{dt} = \frac{d}{dt} [\sin t \hat{i} + \cos t \hat{j} + t \hat{k}] = \cos t \hat{i} - \sin t \hat{j} + 1 \hat{k}$

(ii) $\frac{d^2\vec{r}}{dt^2} = \frac{d}{dt} [\cos t \hat{i} - \sin t \hat{j} + 1 \hat{k}] = -\sin t \hat{i} - \cos t \hat{j} + 0 \hat{k}$

(iii) $\left| \frac{d\vec{r}}{dt} \right| = \sqrt{(\cos t)^2 + (-\sin t)^2 + 1^2} = \sqrt{\cos^2 t + \sin^2 t + 1} = \sqrt{1 + 1} = \sqrt{2}$

(iv) $\left| \frac{d^2\vec{r}}{dt^2} \right| = \sqrt{(-\sin t)^2 + (-\cos t)^2 + 0^2} = \sqrt{\sin^2 t + \cos^2 t + 0} = \sqrt{1} = 1$

Exercise # 3.1

Q#01: Evaluate $\lim_{t \rightarrow t_0} (\sin^2 t \hat{i} + 25 t^3 \hat{j} + \tan t \hat{k})$

Solution: Let $L = \lim_{t \rightarrow t_0} [\sin^2 t \hat{i} + 25 t^3 \hat{j} + \tan t \hat{k}]$

$$L = [\lim_{t \rightarrow t_0} \sin^2 t] \hat{i} + 25 [\lim_{t \rightarrow t_0} t^3] \hat{j} + [\lim_{t \rightarrow t_0} \tan t] \hat{k}$$

$$L = \sin^2 t_0 \hat{i} + 25 t_0^3 \hat{j} + \tan t_0 \hat{k}$$

Q#02: Evaluate $\lim_{t \rightarrow \pi} [\sec t \hat{i} + \cos t \hat{j} + \cot t \hat{k}]$

Solution: Let $L = \lim_{t \rightarrow \pi} [\sec t \hat{i} + \cos t \hat{j} + \cot t \hat{k}]$

$$L = [\lim_{t \rightarrow \pi} \sec t] \hat{i} + [\lim_{t \rightarrow \pi} \cos t] \hat{j} + [\lim_{t \rightarrow \pi} \cot t] \hat{k}$$

$$L = \sin \pi \hat{i} + \cos \pi \hat{j} + \cot \pi \hat{k}$$

$$L = 0 \hat{i} - 1 \hat{j} + \infty \hat{k} = \infty$$

Q#03: Example #01: If the vector function $\vec{f}(t) = \begin{cases} \frac{(a+b)\sin t}{t} \hat{i} + 3\cos t \hat{j} + 16b \frac{\tan t}{t} \hat{k} & \text{if } t \neq 0 \\ 6\hat{i} + 3\hat{j} + 4\hat{k} & \text{if } t = 0 \end{cases}$

Is continuous at $t=0$, then find the value of a and b .

Solution: Since the vector function is continuous at $t=0$. then by definition

$$\lim_{t \rightarrow 0} \vec{f}(t) = \vec{f}(0)$$

$$\Rightarrow \lim_{t \rightarrow 0} \left(\frac{(a+b)\sin t}{t} \hat{i} + 3\cos t \hat{j} + 16b \frac{\tan t}{t} \hat{k} \right) = 6\hat{i} + 3\hat{j} + 4\hat{k}$$

$$(a + b) \left[\lim_{t \rightarrow 0} \frac{\sin t}{t} \right] \hat{i} + 3 \left[\lim_{t \rightarrow 0} \cos t \right] \hat{j} + 16b \left[\lim_{t \rightarrow 0} \frac{\tan t}{t} \right] \hat{k} = 6\hat{i} + 3\hat{j} + 4\hat{k}$$

$$(a + b) [1] \hat{i} + 3 [1] \hat{j} + 16b [1] \hat{k} = 6\hat{i} + 3\hat{j} + 4\hat{k}$$

$$(a + b) \hat{i} + 3 \hat{j} + 16b \hat{k} = 6\hat{i} + 3\hat{j} + 4\hat{k}$$

Comparing coefficients of \hat{i}, \hat{j} & \hat{k}

$$\hat{k}: \quad 16b = 4 \quad \Rightarrow \quad b = \frac{4}{16} \quad \Rightarrow \quad b = \frac{1}{4}$$

$$\hat{i}: \quad a + b = 6 \quad \Rightarrow \quad a + \frac{1}{4} = 6 \quad \Rightarrow \quad a = 6 - \frac{1}{4} = \frac{24-1}{4} \quad \Rightarrow \quad a = \frac{23}{4}$$

Q#04: If the vector function $\vec{f}(t) = \begin{cases} (a + 3b + 2c)t^2 \hat{i} + (2a - b)t^3 \hat{j} + c \hat{k} & \text{if } t \neq 2 \\ \hat{i} + 2\hat{j} + 3\hat{k} & \text{if } t = 2 \end{cases}$

Is continuous at $t=2$, then find the value of a, b & c .

Solution: Since the vector function is continuous at $t = 2$. then by definition

$$\lim_{t \rightarrow 2} \vec{f}(t) = \vec{f}(2)$$

$$\lim_{t \rightarrow 2} [(a + 3b + 2c)t^2 \hat{i} + (2a - b)t^3 \hat{j} + c \hat{k}] = \hat{i} + 2\hat{j} + 3\hat{k}$$

$$(a + 3b + 2c) [\lim_{t \rightarrow 2} t^2] \hat{i} + (2a - b) [\lim_{t \rightarrow 2} t^3] \hat{j} + c [\lim_{t \rightarrow 2} 1] \hat{k} = \hat{i} + 2\hat{j} + 3\hat{k}$$

$$(a + 3b + 2c)(2)^2 \hat{i} + (2a - b)(2)^3 \hat{j} + c [1] \hat{k} = \hat{i} + 2\hat{j} + 3\hat{k}$$

$$4(a + 3b + 2c)\hat{i} + 8(2a - b)\hat{j} + c\hat{k} = \hat{i} + 2\hat{j} + 3\hat{k}$$

Comparing coefficients of \hat{i}, \hat{j} & \hat{k}

\hat{k} : $c = 3$

\hat{i} : $4(a + 3b + 2c) = 1 \Rightarrow 4a + 12b + 8c = 1$

$\Rightarrow 4a + 12b + 8(3) = 1 \Rightarrow 4a + 12b + 24 = 1$

$\Rightarrow 4a + 12b = 1 - 24$

$4a + 12b = -23$ -----(i)

\hat{j} : $8(2a - b) = 2 \Rightarrow 4(2a - b) = 1 \Rightarrow 8a - 4b = 1$

Multiplying by 3: $24a - 12b = 3$ -----(ii)

Adding (i) & (ii) $4a + 12b = -23$

$24a - 12b = 3$

$28a = -20 \Rightarrow a = -20/28 \Rightarrow a = (-5)/7$

using in (ii) $8a - 4b = 1$

$\Rightarrow 8\left(\frac{-5}{7}\right) - 4b = 1$

$\Rightarrow \frac{-40}{7} - 1 = 4b$

$\Rightarrow 4b = \frac{-40-7}{7}$

$\Rightarrow b = (-47)/28$

Q#05: If the vector function $\vec{f}(t) = \begin{cases} (a + 3b + 2c)t^2 \hat{i} + (2a - b)t^3 \hat{j} + (a + b + c)t \hat{k} & \text{if } t \neq 1 \\ 5 \hat{i} + 6 \hat{j} + 3 \hat{k} & \text{if } t = 1 \end{cases}$

Is continuous at $t=1$, then find the value of a, b & c .

Solution: Since the vector function is continuous at $t = 1$. then by definition

$$\lim_{t \rightarrow 1} \vec{f}(t) = \vec{f}(1)$$

$$\lim_{t \rightarrow 1} [(a + 3b + 2c)t^2 \hat{i} + (2a - b)t^3 \hat{j} + (a + b + c)t \hat{k}] = 5 \hat{i} + 6 \hat{j} + 3 \hat{k}$$

$$(a + 3b + 2c)[\lim_{t \rightarrow 1} t^2] \hat{i} + (2a - b)[\lim_{t \rightarrow 1} t^3] \hat{j} + (a + b + c)[\lim_{t \rightarrow 1} t] \hat{k} = 5 \hat{i} + 6 \hat{j} + 3 \hat{k}$$

$$(a + 3b + 2c)(1)^2 \hat{i} + (2a - b)(1)^3 \hat{j} + (a + b + c)[1] \hat{k} = 5 \hat{i} + 6 \hat{j} + 3 \hat{k}$$

$$(a + 3b + 2c)\hat{i} + (2a - b)\hat{j} + (a + b + c)\hat{k} = 5\hat{i} + 6\hat{j} + 3\hat{k}$$

Comparing coefficients of \hat{i}, \hat{j} & \hat{k}

$$a + 3b + 2c = 5 \text{ -----(i)}$$

$$2a - b = 6 \text{ -----(ii)}$$

$$a + b + c = 3$$

Multiplying by 2:

$$2a + 2b + 2c = 6 \text{ -----(iii)}$$

Subtracting (i) & (iii)

$$a + 3b + 2c = 5$$

$$\pm 2a \pm 2b \pm 2c = \pm 6$$

$$-a + b = -1$$

$$b = a - 1 \text{ -----(iv)}$$

Using (iv) in(ii)

$$2a - (a - 1) = 6$$

$$2a - a + 1 = 6$$

$$a = 6 - 1 \quad \Rightarrow \quad a = 5$$

Using $a=5$ in (iv)

$$b = 5 - 1 \quad \Rightarrow \quad b = 4$$

Using $a=5$ & $b=4$ in (iii)

$$a + b + c = 3 \quad \Rightarrow \quad 5 + 4 + c = 3$$

$$c = 3 - 9 \quad \Rightarrow \quad c = -6$$

Q#06: If $\vec{f}(t) = \sin t \hat{i} + \cos t \hat{j} + 9 \hat{k}$. Find $|\vec{f}(t)|$

Solution: Given $\vec{f}(t) = \sin t \hat{i} + \cos t \hat{j} + 9 \hat{k}$.

Now $|\vec{f}(t)| = \sqrt{(\cos t)^2 + (-\sin t)^2 + 9^2} = \sqrt{\cos^2 t + \sin^2 t + 81} = \sqrt{1 + 81}$

$$|\vec{f}(t)| = \sqrt{82}$$

Q#07: If $\vec{f}(t) = \hat{i} + 2 \tan t \hat{j} + 2 \tan^2 t \hat{k}$. Find $|\vec{f}(t)|$

Solution: Given $\vec{f}(t) = \hat{i} + 2 \tan t \hat{j} + 2 \tan^2 t \hat{k}$

Now $|\vec{f}(t)| = \sqrt{(1)^2 + (2 \tan t)^2 + (2 \tan^2 t)^2} = \sqrt{(1)^2 + 4 \tan^2 t + (2 \tan^2 t)^2}$
 $= \sqrt{(1)^2 + 2(1)(2 \tan^2 t) + (2 \tan^2 t)^2} = \sqrt{(1 + 2 \tan^2 t)^2}$

$$|\vec{f}(t)| = 1 + 2 \tan^2 t$$

Q#08: If $\vec{f}(t) = t^2 \hat{i} + (t-1) \hat{j} + (t^2 + t + 1) \hat{k}$ & $\vec{g}(t) = (t^2 + 1) \hat{i} + t \hat{j} - \hat{k}$ Find (i) $\vec{f}(t) \cdot \vec{g}(t)$ (ii) $\vec{f}(t) \times \vec{g}(t)$

Solution: Given that $\vec{f}(t) = t^2 \hat{i} + (t-1) \hat{j} + (t^2 + t + 1) \hat{k}$ & $\vec{g}(t) = (t^2 + 1) \hat{i} + t \hat{j} - \hat{k}$

(i) $\vec{f}(t) \cdot \vec{g}(t) = [t^2 \hat{i} + (t-1) \hat{j} + (t^2 + t + 1) \hat{k}] \cdot [(t^2 + 1) \hat{i} + t \hat{j} - \hat{k}]$
 $= t^2 (t^2 + 1) + (t-1)t + (t^2 + t + 1)(-1) = t^4 + t^2 + t^2 - t - t^2 - t - 1$
 $= t^4 + t^2 - 2t - 1$

(ii) $\vec{f}(t) \times \vec{g}(t) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ t^2 & t-1 & t^2+t+1 \\ t^2+1 & t & -1 \end{vmatrix}$
 $= \hat{i} \begin{vmatrix} t-1 & t^2+t+1 \\ t & -1 \end{vmatrix} - \hat{j} \begin{vmatrix} t^2 & t^2+t+1 \\ t^2+1 & -1 \end{vmatrix} + \hat{k} \begin{vmatrix} t^2 & t-1 \\ t^2+1 & t \end{vmatrix}$
 $= \hat{i} [(-1)(t-1) - t(t^2+t+1)] - \hat{j} [(-1)t^2 - (t^2+1)(t^2+t+1)] + \hat{k} [t \cdot t^2 - (t^2+1)(t-1)]$
 $= \hat{i} [-t+1 - t^3 - t^2 - t] - \hat{j} [-t^2 - t^4 - t^3 - t^2 - t^2 - t - 1] + \hat{k} [t^3 - t^3 + t^2 - t + 1]$
 $= \hat{i} [-2t - t^3 - t^2 + 1] + \hat{j} [3t^2 + t^4 + t^3 + t + 1] + \hat{k} [t^2 - t + 1]$
 $= [1 - 2t - t^2 - t^3] \hat{i} - [1 + t^3 t^2 + t^3 + t^4] \hat{j} + [1 - t + t^2] \hat{k}$

Q#09: if $\vec{f}(t) = \cos t \hat{i} + \sin t \hat{j} + t^2 \sec t \hat{k}$. calculate $|\vec{f}'(t)|^2$

Solution: Given $\vec{f}(t) = \cos t \hat{i} + \sin t \hat{j} + t^2 \sec t \hat{k}$

Differentiate w. r. t t

$$\vec{f}'(t) = -\sin t \hat{i} + \cos t \hat{j} + [t^2 \sec t \cdot \tan t + 2t \sec t] \hat{k}$$

Now $|\vec{f}'(t)| = \sqrt{(-\sin t)^2 + (\cos t)^2 + (t^2 \sec t \cdot \tan t + 2t \sec t)^2}$

$$= \sqrt{\sin^2 t + \cos^2 t + (t^2 \sec t \cdot \tan t + 2t \sec t)^2}$$

$$|\vec{f}'(t)| = \sqrt{1 + (t^2 \sec t \cdot \tan t + 2t \sec t)^2}$$

Taking square on both sides

$$|\vec{f}'(t)|^2 = 1 + (t^2 \sec t \cdot \tan t + 2t \sec t)^2$$

Q#10: If $\vec{f}(t) = (t^2 + 2t - 1)\hat{i} + (3t^2 - 2)\hat{j} + (5 - 6t)\hat{k}$ Find (i) $\vec{f}'(t)$ (ii) $\vec{f}''(t)$

Solution: Given $\vec{f}(t) = (t^2 + 2t - 1)\hat{i} + (3t^2 - 2)\hat{j} + (5 - 6t)\hat{k}$

(i) **Differentiate w. r. t t**

$$\vec{f}'(t) = (2t + 2)\hat{i} + (6t)\hat{j} + (-6)\hat{k} = (2t + 2)\hat{i} + 6t\hat{j} - 6\hat{k}$$

(ii) **Again Differentiate w. r. t t**

$$\vec{f}''(t) = 2\hat{i} + 6\hat{j} + 0\hat{k}$$

Q#11: if $\vec{f}(t) = \cos t \hat{i} + \sin t \hat{j} + 8 \hat{k}$. Show that $\vec{f}'(t) \cdot \vec{f}''(t) = 0$

Solution: Given $\vec{f}(t) = \cos t \hat{i} + \sin t \hat{j} + 8 \hat{k}$

Differentiate w. r. t t $\vec{f}'(t) = -\sin t \hat{i} + \cos t \hat{j} + 0\hat{k}$

Again Differentiate w. r. t t $\vec{f}''(t) = -\cos t \hat{i} - \sin t \hat{j} + 0\hat{k}$

Now

$$\vec{f}'(t) \cdot \vec{f}''(t) = (-\sin t \hat{i} + \cos t \hat{j} + 0\hat{k}) \cdot (-\cos t \hat{i} - \sin t \hat{j} + 0\hat{k})$$

$$= (-\sin t)(-\cos t) + (\cos t)(-\sin t) + (0)(0)$$

$$= \sin t \cdot \cos t - \sin t \cdot \cos t + 0$$

Hence proved $\vec{f}'(t) \cdot \vec{f}''(t) = 0$.

Q#12: If $\vec{f}(t) = (t - \sin t)\hat{i} + (1 - \cos t)\hat{j} + (t \sin t + \cos t)\hat{k}$. Find $\vec{f}'(t)$ & $\vec{f}''(t)$ at $t=0$ & $t = \frac{\pi}{2}$.

Solution: Given $\vec{f}(t) = (t - \sin t)\hat{i} + (1 - \cos t)\hat{j} + (t \sin t + \cos t)\hat{k}$.

Differentiate w. r. t t

$$\vec{f}'(t) = (1 - \cos t)\hat{i} - (-\sin t)\hat{j} + (t \cos t + \sin t - \sin t)\hat{k}$$

$$\vec{f}'(t) = (1 - \cos t)\hat{i} + \sin t\hat{j} + t \cos t\hat{k}$$

At $t = 0$: $\vec{f}'(t) = (1 - 1)\hat{i} + 0\hat{j} + 0\hat{k} = 0\hat{i} + 0\hat{j} + 0\hat{k}$

At $t = \frac{\pi}{2}$: $\vec{f}'(t) = (1 - 0)\hat{i} + 1\hat{j} + 0\hat{k} = 1\hat{i} + 1\hat{j} + 0\hat{k}$

Again Differentiate w. r. t t

$$\vec{f}''(t) = (0 + \sin t)\hat{i} + \cos t\hat{j} + (\cos t - t \sin t)\hat{k}$$

$$\vec{f}''(t) = \sin t\hat{i} + \cos t\hat{j} + (\cos t - t \sin t)\hat{k}$$

At $t = 0$: $\vec{f}''(t) = 0\hat{i} + 1\hat{j} + 1\hat{k}$

At $t = \frac{\pi}{2}$: $\vec{f}''(t) = 1\hat{i} + 0\hat{j} + (0 - \frac{\pi}{2})\hat{k} = 1\hat{i} + 0\hat{j} - \frac{\pi}{2}\hat{k}$

Q#13: If $\vec{f}(t) = \left(\frac{t^2+1}{t}\right)\hat{i} + \left(\frac{1}{1+t}\right)\hat{j} + t\hat{k}$. Find $\vec{f}'(t)$ and $\vec{f}(t) \cdot \vec{f}'(t)$.

Solution: Given $\vec{f}(t) = \left(\frac{t^2+1}{t}\right)\hat{i} + \left(\frac{1}{1+t}\right)\hat{j} + t\hat{k}$ **Then**

$$\vec{f}'(t) = \left(\frac{t(2t) - (t^2+1)1}{t^2}\right)\hat{i} + \left(\frac{-1}{(1+t)^2}\right)\hat{j} + 1\hat{k}$$

$$= \left(\frac{2t^2 - t^2 - 1}{t^2}\right)\hat{i} - \frac{1}{(1+t)^2}\hat{j} + 1\hat{k}$$

$$\vec{f}'(t) = \left(\frac{t^2-1}{t^2}\right)\hat{i} - \frac{1}{(1+t)^2}\hat{j} + 1\hat{k}$$

Now

$$\vec{f}(t) \cdot \vec{f}'(t) = \left[\left(\frac{t^2+1}{t}\right)\hat{i} + \left(\frac{1}{1+t}\right)\hat{j} + t\hat{k}\right] \cdot \left[\left(\frac{t^2-1}{t^2}\right)\hat{i} - \frac{1}{(1+t)^2}\hat{j} + 1\hat{k}\right]$$

$$= \left(\frac{t^2+1}{t}\right)\left(\frac{t^2-1}{t^2}\right) + \left(\frac{1}{1+t}\right)\left(\frac{-1}{(1+t)^2}\right) + (t)(1)$$

$$\vec{f}(t) \cdot \vec{f}'(t) = \frac{t^4-1}{t^3} - \frac{1}{(1+t)^3} + t$$

Q#14: If $\vec{f}(t)$ & $\vec{g}(t)$ are continuous at $t = t_0$. Prove that $\vec{f}(t) + \vec{g}(t)$ is also continuous at $t = t_0$.

Solution: Given $\vec{f}(t)$ & $\vec{g}(t)$ are continuous at $t = t_0$

Then there exist a number $\epsilon > 0$. $|\vec{f}(t) - \vec{f}(t_0)| < \epsilon$ -----(i)

And $|\vec{g}(t) - \vec{g}(t_0)| < \epsilon$ -----(ii)

Adding (i) & (ii) $|\vec{f}(t) - \vec{f}(t_0)| + |\vec{g}(t) - \vec{g}(t_0)| < \epsilon + \epsilon$

$|\vec{f}(t) + \vec{g}(t) - [\vec{f}(t_0) + \vec{g}(t_0)]| < 2\epsilon$

Here $2\epsilon > 0$ Then show that $\vec{f}(t) + \vec{g}(t)$ is also continuous at $t = t_0$.

Q#15: Is $\vec{f}(t) = t\hat{i} + t^2\hat{j} + \frac{1}{t}\hat{k}$ is continuous function at $t=0$?

Solution: Given $\vec{f}(t) = t\hat{i} + t^2\hat{j} + \frac{1}{t}\hat{k}$

Now $\lim_{t \rightarrow 0^+} \vec{f}(t) = \lim_{t \rightarrow 0^+} [t\hat{i} + t^2\hat{j} + \frac{1}{t}\hat{k}] = +0\hat{i} + (+0)^2\hat{j} + \frac{1}{+0}\hat{k} = +0\hat{i} + 0\hat{j} + \infty\hat{k} = \infty$ -----(i)

$\lim_{t \rightarrow 0^-} \vec{f}(t) = \lim_{t \rightarrow 0^-} [t\hat{i} + t^2\hat{j} + \frac{1}{t}\hat{k}] = -0\hat{i} + (-0)^2\hat{j} + \frac{1}{-0}\hat{k} = -0\hat{i} + 0\hat{j} - \infty\hat{k} = -\infty$ -----(ii)

$\vec{f}(0) = 0\hat{i} + 0\hat{j} + \frac{1}{0}\hat{k} = 0\hat{i} + 0\hat{j} + \infty\hat{k} = \infty$ -----(iii)

From (i), (ii) & (iii) this shows that the given vector function is discontinuous at $t = 0$.

Q#16: If ω, a, b are constant and if $\vec{f}(t) = a \cos \omega t + b \sin \omega t$. Show that $\vec{f}''(t) + \omega^2 \vec{f}(t) = 0$

Solution: Given $\vec{f}(t) = a \cos \omega t + b \sin \omega t$ -----(i)

Differentiate w. r. t t $\vec{f}'(t) = -a \omega \sin \omega t + b \omega \cos \omega t$

Again differentiate w. r. t t $\vec{f}''(t) = -a \omega^2 \cos \omega t - b \omega^2 \sin \omega t$

$\vec{f}''(t) = -\omega^2 [a \cos \omega t + b \sin \omega t]$

$\vec{f}''(t) = -\omega^2 \vec{f}(t)$ \therefore From (i)

$\vec{f}''(t) + \omega^2 \vec{f}(t) = 0$ Hence proved.

Rules of Differentiation:

If \vec{a}, \vec{b} & \vec{c} are differentiable function of scalar variable t .

(i) $\frac{d}{dt} [\vec{a} + \vec{b}] = \frac{d\vec{a}}{dt} + \frac{d\vec{b}}{dt}$

(ii) $\frac{d}{dt} [\vec{a} \cdot \vec{b}] = \frac{d\vec{a}}{dt} \cdot \vec{b} + \vec{a} \cdot \frac{d\vec{b}}{dt}$

(iii) $\frac{d}{dt} [\vec{a} \times \vec{b}] = \frac{d\vec{a}}{dt} \times \vec{b} + \vec{a} \times \frac{d\vec{b}}{dt}$

(iv) $\frac{d}{dt} [\varphi \vec{a}] = \frac{d\varphi}{dt} \vec{a} + \varphi \frac{d\vec{a}}{dt}$

(v) $\frac{d}{dt} [\vec{a} \cdot (\vec{b} \times \vec{c})] = \frac{d\vec{a}}{dt} \cdot (\vec{b} \times \vec{c}) + \vec{a} \cdot \left(\frac{d\vec{b}}{dt} \times \vec{c} \right) + \vec{a} \cdot (\vec{b} \times \frac{d\vec{c}}{dt})$

(vi) $\frac{d}{dt} [\vec{a} \times (\vec{b} \times \vec{c})] = \frac{d\vec{a}}{dt} \times (\vec{b} \times \vec{c}) + \vec{a} \times \left(\frac{d\vec{b}}{dt} \times \vec{c} \right) + \vec{a} \times (\vec{b} \times \frac{d\vec{c}}{dt})$

(vii) **Derivative of a constant vector:**

Let \vec{r} be constant vector. Then $\frac{d\vec{r}}{dt} = 0$

(viii) **Derivative of a vector function in terms of its component.**

Let $\vec{r}(t) = x(t)\hat{i} + y(t)\hat{j} + z(t)\hat{k}$ Then $\frac{d\vec{r}}{dt} = \frac{dx}{dt}\hat{i} + \frac{dy}{dt}\hat{j} + \frac{dz}{dt}\hat{k}$

Theorem #I :

Show that Necessary and sufficient condition for a vector \vec{a} of scalar variable t to be a constant is $\frac{d\vec{a}}{dt} = 0$.

Proof: By given condition. That \vec{a} be constant vector. i.e.

$\vec{a} = \text{constant}$

Differentiate w.r.t t $\frac{d\vec{a}}{dt} = \frac{d}{dt}(\text{constant}) \Rightarrow \frac{d\vec{a}}{dt} = 0$

Conversely, suppose that $\frac{d\vec{a}}{dt} = 0 \Rightarrow d\vec{a} = 0 dt$

on integrating both sides $\int d\vec{a} = \int 0 dt$

$\vec{a} = 0 \cdot t + \text{constant} \Rightarrow \vec{a} = \text{constant}$

Hence prove that

The Necessary and sufficient condition for a vector \vec{a} of scalar variable t to be a constant is $\frac{d\vec{a}}{dt} = 0$.

Theorem #II: Show that Necessary and sufficient condition for a vector \vec{a} of scalar variable t to have a constant magnitude is $\vec{a} \cdot \frac{d\vec{a}}{dt} = 0$.

Proof: By given condition. That vector \vec{a} have a constant magnitude.

$$|\vec{a}| = \text{constant}$$

Taking square on both sides

$$|\vec{a}|^2 = (\text{constant})^2 = \text{constant}$$

We know that $\vec{a} \cdot \vec{a} = |\vec{a}|^2$

$$\vec{a} \cdot \vec{a} = \text{constant}$$

Differentiate w.r.t t

$$\frac{d}{dt}(\vec{a} \cdot \vec{a}) = \frac{d}{dt}(\text{constant})$$

$$\frac{d\vec{a}}{dt} \cdot \vec{a} + \vec{a} \cdot \frac{d\vec{a}}{dt} = 0$$

$$2 \vec{a} \cdot \frac{d\vec{a}}{dt} = 0$$

$$\therefore \vec{a} \cdot \frac{d\vec{a}}{dt} = \frac{d\vec{a}}{dt} \cdot \vec{a}$$

$$\vec{a} \cdot \frac{d\vec{a}}{dt} = 0$$

Conversely, suppose that

$$\vec{a} \cdot \frac{d\vec{a}}{dt} = 0$$

$$\therefore \vec{a} \cdot \frac{d\vec{a}}{dt} = a \frac{da}{dt}$$

$$a \frac{da}{dt} = 0$$

$$a da = 0 dt$$

on integrating both sides

$$\int a da = \int 0 dt$$

$$\frac{|\vec{a}|^2}{2} = 0 \cdot t + \text{constant}$$

$$|\vec{a}|^2 = 2(\text{constant})$$

Taking square-root on both sides

$$|\vec{a}| = \sqrt{2(\text{constant})}$$

$$|\vec{a}| = \text{constant}$$

Hence prove that

The Necessary and sufficient condition for a vector \vec{a} of scalar variable t to have a constant

magnitude is $\vec{a} \cdot \frac{d\vec{a}}{dt} = 0$

Theorem #III: Show that Necessary and sufficient condition for a vector \vec{a} of scalar variable t to have a constant direction is $\vec{a} \times \frac{d\vec{a}}{dt} = 0$.

Proof: Let \hat{r} be unit vector in the direction of vector \vec{a} .

By given condition, that direction is constant $\therefore \hat{r} = \text{constant}$

Then $\frac{d\hat{r}}{dt} = 0$ -----(i)

As we know that $\hat{r} = \frac{\vec{a}}{a} \implies \vec{a} = a \hat{r}$ -----(ii) $\therefore |\vec{a}| = a$

Differentiate w.r.t t $\frac{d\vec{a}}{dt} = \frac{d}{dt} (a \hat{r}) = \frac{da}{dt} \hat{r} + a \frac{d\hat{r}}{dt}$ -----(iii)

Taking cross product of equation (ii) & (iii)

$$\vec{a} \times \frac{d\vec{a}}{dt} = a \hat{r} \times \left(\frac{da}{dt} \hat{r} + a \frac{d\hat{r}}{dt} \right) = a \frac{da}{dt} (\hat{r} \times \hat{r}) + a^2 \left(\hat{r} \times \frac{d\hat{r}}{dt} \right)$$

$$\vec{a} \times \frac{d\vec{a}}{dt} = a \frac{da}{dt} (0) + a^2 \left(\hat{r} \times \frac{d\hat{r}}{dt} \right) \therefore \hat{r} \times \hat{r} = 0$$

$$\vec{a} \times \frac{d\vec{a}}{dt} = 0 + a^2 \left(\hat{r} \times \frac{d\hat{r}}{dt} \right)$$

$$\vec{a} \times \frac{d\vec{a}}{dt} = a^2 \left(\hat{r} \times \frac{d\hat{r}}{dt} \right)$$
 -----(iv)

$$\vec{a} \times \frac{d\vec{a}}{dt} = a^2 (\hat{r} \times 0) \qquad \therefore \text{From (i)} \quad \frac{d\hat{r}}{dt} = 0$$

$$\vec{a} \times \frac{d\vec{a}}{dt} = 0$$

Conversely, suppose that

$$\vec{a} \times \frac{d\vec{a}}{dt} = 0$$

Then equation (iv) will become $a^2 \left(\hat{r} \times \frac{d\hat{r}}{dt} \right) = 0 \implies \hat{r} \times \frac{d\hat{r}}{dt} = 0$

Here $\hat{r} \neq 0$ but $\frac{d\hat{r}}{dt} = 0$ Therefore $\hat{r} = \text{constant}$

Hence prove that

The Necessary and sufficient condition for a vector \vec{a} of scalar variable t to have a constant direction

is $\vec{a} \times \frac{d\vec{a}}{dt} = 0$.

Example#01: $\vec{r} = (t + 1)\hat{i} + (t^2 + t + 1)\hat{j} + (t^3 + t^2 + t + 1)\hat{k}$. Find $\frac{d\vec{r}}{dt}$ & $\frac{d^2\vec{r}}{dt^2}$.

Solution: Given vector function is $\vec{r} = (t + 1)\hat{i} + (t^2 + t + 1)\hat{j} + (t^3 + t^2 + t + 1)\hat{k}$

Then $\frac{d\vec{r}}{dt} = (1)\hat{i} + (2t + 1)\hat{j} + (3t^2 + 2t + 1)\hat{k}$ & $\frac{d^2\vec{r}}{dt^2} = 0\hat{i} + 2\hat{j} + (6t + 2)\hat{k}$

Example#02: $\vec{f}(t) = \sin t\hat{i} + \cos t\hat{j} + t\hat{k}$. Find (i) $\vec{f}'(t)$ (ii) $\vec{f}''(t)$ (iii) $|\vec{f}'(t)|$ (iv) $|\vec{f}''(t)|$.

Solution: Given vector function is

$$\vec{f}(t) = \sin t\hat{i} + \cos t\hat{j} + t\hat{k}$$

(i) $\vec{f}'(t) = \cos t\hat{i} - \sin t\hat{j} + 1\hat{k}$

(ii) $\vec{f}''(t) = -\sin t\hat{i} - \cos t\hat{j} + 0\hat{k}$

(iii) $|\vec{f}'(t)| = \sqrt{(\cos t)^2 + (-\sin t)^2 + 1^2} = \sqrt{\cos^2 t + \sin^2 t + 1} = \sqrt{1 + 1} = \sqrt{2}$

(iv) $|\vec{f}''(t)| = \sqrt{(-\sin t)^2 + (-\cos t)^2 + 0^2} = \sqrt{\sin^2 t + \cos^2 t + 0} = \sqrt{1} = 1$

Example#03: If $\vec{r} = \cos nt\hat{i} + \sin nt\hat{j}$. Where n is a constant. show that $\vec{r} \times \frac{d\vec{r}}{dt} = n\hat{k}$.

Solution: Given vector function is $\vec{r} = \cos nt\hat{i} + \sin nt\hat{j}$ Then $\frac{d\vec{r}}{dt} = -n\sin nt\hat{i} + n\cos nt\hat{j}$

Now
$$\vec{r} \times \frac{d\vec{r}}{dt} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \cos nt & \sin nt & 0 \\ -n\sin nt & n\cos nt & 0 \end{vmatrix} = 0\hat{i} - 0\hat{j} + \hat{k} \begin{vmatrix} \cos nt & \sin nt \\ -n\sin nt & n\cos nt \end{vmatrix}$$

$$= \hat{k} [(n\cos nt)(\cos nt) - (-n\sin nt)(\sin nt)]$$

$$= n\hat{k} [\cos^2 nt + \sin^2 nt]$$

$\vec{r} \times \frac{d\vec{r}}{dt} = n\hat{k}$ **Hence proved**

Example#04: If \vec{a} be differentiable vector function of scalar variable t then show that $\frac{d}{dt}(\vec{a} \times \frac{d\vec{a}}{dt}) = \vec{a} \times \frac{d^2\vec{a}}{dt^2}$

Solution:
$$L.H.S = \frac{d}{dt}(\vec{a} \times \frac{d\vec{a}}{dt}) = \frac{d\vec{a}}{dt} \times \frac{d\vec{a}}{dt} + \vec{a} \times \frac{d^2\vec{a}}{dt^2}$$

$$= 0 + \vec{a} \times \frac{d^2\vec{a}}{dt^2} \qquad \therefore \frac{d\vec{a}}{dt} \times \frac{d\vec{a}}{dt} = 0$$

$$= \vec{a} \times \frac{d^2\vec{a}}{dt^2} = R.H.S$$

Hence proved L.H.S = R.H.S

Example#05: If \vec{a} , \vec{b} are constant vectors, ω is a constant and \vec{r} be a vector function is given by

$$\vec{r} = \cos \omega t \vec{a} + \sin \omega t \vec{b}. \text{ Then Show that (i) } \frac{d^2\vec{r}}{dt^2} + \omega^2 \vec{r} = 0 \text{ (ii) } \vec{r} \times \frac{d\vec{r}}{dt} = \omega (\vec{a} \times \vec{b})$$

Solution: Given vector function $\vec{r} = \cos \omega t \vec{a} + \sin \omega t \vec{b}$ -----(i)

Then $\frac{d\vec{r}}{dt} = -\omega \sin \omega t \vec{a} + \omega \cos \omega t \vec{b}$ -----(ii)

(i) $\frac{d^2\vec{r}}{dt^2} = -\omega^2 \cos \omega t \vec{a} - \omega^2 \sin \omega t \vec{b}$

$$\frac{d^2\vec{r}}{dt^2} = -\omega^2 [\cos \omega t \vec{a} + \sin \omega t \vec{b}]$$

$$\frac{d^2\vec{r}}{dt^2} = -\omega^2 \vec{r} \quad \Rightarrow \quad \frac{d^2\vec{r}}{dt^2} + \omega^2 \vec{r} = 0 \quad \text{Hence proved.}$$

(ii) Now taking cross product of equation (i) & (ii)

$$\begin{aligned} \vec{r} \times \frac{d\vec{r}}{dt} &= (\cos \omega t \vec{a} + \sin \omega t \vec{b}) \times (-\omega \sin \omega t \vec{a} + \omega \cos \omega t \vec{b}) \\ &= -\omega \cos \omega t \sin \omega t (\vec{a} \times \vec{a}) + \omega \cos^2 \omega t (\vec{a} \times \vec{b}) + \omega \sin^2 \omega t (-\vec{b} \times \vec{a}) + \omega \cos \omega t \sin \omega t (\vec{b} \times \vec{b}) \\ &= -\omega \cos \omega t \sin \omega t (0) + \omega \cos^2 \omega t (\vec{a} \times \vec{b}) + \omega \sin^2 \omega t (\vec{a} \times \vec{b}) + \omega \cos \omega t \sin \omega t (0) \\ &= 0 + \omega (\vec{a} \times \vec{b}) [\cos^2 \omega t + \sin^2 \omega t] + 0 \end{aligned}$$

$$\vec{r} \times \frac{d\vec{r}}{dt} = \omega (\vec{a} \times \vec{b}) \quad \text{Hence proved.}$$

Example# 06: if $\frac{d\vec{u}}{dt} = \vec{\omega} \times \vec{u}$ & $\frac{d\vec{r}}{dt} = \vec{\omega} \times \vec{r}$. Then show that $\frac{d}{dt} (\vec{u} \times \vec{r}) = \vec{\omega} \times (\vec{u} \times \vec{r})$.

Solution: Taking L.H.S $\frac{d}{dt} (\vec{u} \times \vec{r}) = \frac{d\vec{u}}{dt} \times \vec{r} + \vec{u} \times \frac{d\vec{r}}{dt}$

Using given values $\frac{d\vec{u}}{dt} = \vec{\omega} \times \vec{u}$ & $\frac{d\vec{r}}{dt} = \vec{\omega} \times \vec{r}$

$$\begin{aligned} \frac{d}{dt} (\vec{u} \times \vec{r}) &= (\vec{\omega} \times \vec{u}) \times \vec{r} + \vec{u} \times (\vec{\omega} \times \vec{r}) \\ &= (\vec{\omega} \cdot \vec{r}) \vec{u} - (\vec{u} \cdot \vec{r}) \vec{\omega} + (\vec{u} \cdot \vec{r}) \vec{\omega} - (\vec{u} \cdot \vec{\omega}) \vec{r} \end{aligned}$$

$$\frac{d}{dt} (\vec{u} \times \vec{r}) = (\vec{\omega} \cdot \vec{r}) \vec{u} - (\vec{u} \cdot \vec{\omega}) \vec{r} \text{ -----(i)}$$

Now taking R.H.S $\vec{\omega} \times (\vec{u} \times \vec{r}) = (\vec{\omega} \cdot \vec{r}) \vec{u} - (\vec{u} \cdot \vec{\omega}) \vec{r}$ -----(ii)

From (i) & (ii) Hence proved that

$$\frac{d}{dt} (\vec{u} \times \vec{r}) = \vec{\omega} \times (\vec{u} \times \vec{r})$$

Example: 07: Differentiate the following w. r. t t , where \vec{r} vector function of scalar variable t .

\vec{a} be constant vector and m is any scalar. (i) $\vec{r} \cdot \vec{a}$ (ii) $\vec{r} \times \vec{a}$ (iii) $\vec{r} \cdot \frac{d\vec{r}}{dt}$

(iv) $\vec{r} \times \frac{d\vec{r}}{dt}$ (v) $r^2 + \frac{1}{r^2}$ (vi) $m \left(\frac{d\vec{r}}{dt}\right)^2$ (vii) $\frac{\vec{r} + \vec{a}}{r^2 + a^2}$ (viii) $\frac{\vec{r} \times \vec{a}}{\vec{r} \cdot \vec{a}}$

(i) Let $\vec{f}(t) = \vec{r} \cdot \vec{a}$

Differentiate w.r.t t $\vec{f}'(t) = \frac{d}{dt} (\vec{r} \cdot \vec{a}) = \frac{d\vec{r}}{dt} \cdot \vec{a} + \vec{r} \cdot \frac{d\vec{a}}{dt} \Rightarrow \vec{f}'(t) = \frac{d\vec{r}}{dt} \cdot \vec{a} \because \frac{d\vec{a}}{dt} = 0$

(ii) Let $\vec{f}(t) = \vec{r} \times \vec{a}$

Differentiate w.r.t t $\vec{f}'(t) = \frac{d}{dt} (\vec{r} \times \vec{a}) = \frac{d\vec{r}}{dt} \times \vec{a} + \vec{r} \times \frac{d\vec{a}}{dt} \Rightarrow \vec{f}'(t) = \frac{d\vec{r}}{dt} \times \vec{a} \because \frac{d\vec{a}}{dt} = 0$

(iii) Let $\vec{f}(t) = \vec{r} \cdot \frac{d\vec{r}}{dt}$

Differentiate w.r.t t $\vec{f}'(t) = \frac{d}{dt} \left(\vec{r} \cdot \frac{d\vec{r}}{dt}\right) = \frac{d\vec{r}}{dt} \cdot \frac{d\vec{r}}{dt} + \vec{r} \cdot \frac{d^2\vec{r}}{dt^2} \Rightarrow \vec{f}'(t) = \left(\frac{d\vec{r}}{dt}\right)^2 + \vec{r} \cdot \frac{d^2\vec{r}}{dt^2} \because \frac{d\vec{r}}{dt} \cdot \frac{d\vec{r}}{dt} = \left(\frac{d\vec{r}}{dt}\right)^2$

(iv) Let $\vec{f}(t) = \vec{r} \times \frac{d\vec{r}}{dt}$

Differentiate w.r.t t $\vec{f}'(t) = \frac{d}{dt} \left(\vec{r} \times \frac{d\vec{r}}{dt}\right) = \frac{d\vec{r}}{dt} \times \frac{d\vec{r}}{dt} + \vec{r} \times \frac{d^2\vec{r}}{dt^2}$

$$\vec{f}'(t) = 0 + \vec{r} \times \frac{d^2\vec{r}}{dt^2}$$

$$\vec{f}'(t) = \vec{r} \times \frac{d^2\vec{r}}{dt^2} \because \frac{d\vec{r}}{dt} \times \frac{d\vec{r}}{dt} = 0$$

(v) Let $\vec{f}(t) = r^2 + \frac{1}{r^2}$

Differentiate w.r.t t $\vec{f}'(t) = \frac{d}{dt} \left(r^2 + \frac{1}{r^2}\right) = \frac{d}{dt} (r^2) + \frac{d}{dt} (r^{-2}) = 2r \frac{dr}{dt} + \left(-2r^{-3} \frac{dr}{dt}\right)$

$$\vec{f}'(t) = 2r \frac{dr}{dt} - \frac{2}{r^3} \frac{dr}{dt} = 2 \frac{dr}{dt} \left(r - \frac{2}{r^3}\right)$$

(vi) Let $\vec{f}(t) = m \left(\frac{d\vec{r}}{dt}\right)^2$

Differentiate w.r.t t $\vec{f}'(t) = m \frac{d}{dt} \left(\frac{d\vec{r}}{dt}\right)^2 = 2m \left(\frac{d\vec{r}}{dt}\right) \left[\frac{d}{dt} \left(\frac{d\vec{r}}{dt}\right)\right] \Rightarrow \vec{f}'(t) = 2m \frac{d\vec{r}}{dt} \frac{d^2\vec{r}}{dt^2}$

(vii) Let $\vec{f}(t) = \frac{\vec{r} + \vec{a}}{r^2 + a^2}$

Differentiate w.r.t t

$$\vec{f}'(t) = \frac{d}{dt} \left(\frac{\vec{r} + \vec{a}}{r^2 + a^2}\right) = \frac{(r^2 + a^2) \frac{d}{dt} (\vec{r} + \vec{a}) - (\vec{r} + \vec{a}) \frac{d}{dt} (r^2 + a^2)}{(r^2 + a^2)^2} = \frac{(r^2 + a^2) \left[\frac{d\vec{r}}{dt} + \frac{d\vec{a}}{dt}\right] - (\vec{r} + \vec{a}) \left[2r \frac{dr}{dt}\right]}{(r^2 + a^2)^2} \because \frac{d\vec{a}}{dt} = 0$$

(viii) Let $\vec{f}(t) = \frac{\vec{r} \times \vec{a}}{\vec{r} \cdot \vec{a}}$

Differentiate w.r.t t

$$\vec{f}'(t) = \frac{d}{dt} \left(\frac{\vec{r} \times \vec{a}}{\vec{r} \cdot \vec{a}} \right) = \frac{(\vec{r} \cdot \vec{a}) \frac{d}{dt} (\vec{r} \times \vec{a}) - (\vec{r} \times \vec{a}) \frac{d}{dt} (\vec{r} \cdot \vec{a})}{(\vec{r} \cdot \vec{a})^2} = \frac{(\vec{r} \cdot \vec{a}) \left[\frac{d\vec{r}}{dt} \times \vec{a} + \vec{r} \times \frac{d\vec{a}}{dt} \right] - (\vec{r} \times \vec{a}) \left[\frac{d\vec{r}}{dt} \cdot \vec{a} + \vec{r} \cdot \frac{d\vec{a}}{dt} \right]}{(\vec{r} \cdot \vec{a})^2}$$

$$\vec{f}'(t) = \frac{(\vec{r} \cdot \vec{a}) \left[\frac{d\vec{r}}{dt} \times \vec{a} + 0 \right] - (\vec{r} \times \vec{a}) \left[\frac{d\vec{r}}{dt} \cdot \vec{a} + 0 \right]}{(\vec{r} \cdot \vec{a})^2} \quad \therefore \frac{d\vec{a}}{dt} = 0$$

$$\vec{f}'(t) = \frac{(\vec{r} \cdot \vec{a}) \left[\frac{d\vec{r}}{dt} \times \vec{a} \right] - (\vec{r} \times \vec{a}) \left[\frac{d\vec{r}}{dt} \cdot \vec{a} \right]}{(\vec{r} \cdot \vec{a})^2}$$

$$\vec{f}'(t) = \frac{(\vec{r} \cdot \vec{a}) \left[\frac{d\vec{r}}{dt} \times \vec{a} \right]}{(\vec{r} \cdot \vec{a})^2} - \frac{(\vec{r} \times \vec{a}) \left[\frac{d\vec{r}}{dt} \cdot \vec{a} \right]}{(\vec{r} \cdot \vec{a})^2} = \frac{\left[\frac{d\vec{r}}{dt} \times \vec{a} \right]}{(\vec{r} \cdot \vec{a})} - \frac{(\vec{r} \times \vec{a}) \left[\frac{d\vec{r}}{dt} \cdot \vec{a} \right]}{(\vec{r} \cdot \vec{a})^2}$$

Example#08: A particle that move along a curve . $x = 4 \cos t, y = 4 \sin t, z = 6t$. Find velocity and acceleration at $t = 0$ & $t = \frac{\pi}{2}$.

Solution: Let $\vec{r}(t)$ be a position vector. Then

$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$$

Putting $x = 4 \cos t, y = 4 \sin t, z = 6t$, we get

$$\vec{r} = 4 \cos t \hat{i} + 4 \sin t \hat{j} + 6t \hat{k}$$

Velocity: Differentiate \vec{r} w. r. t t .

$$\vec{v} = \frac{d\vec{r}}{dt} = -4 \sin t \hat{i} + 4 \cos t \hat{j} + 6 \hat{k}$$

At $t = 0$: $\vec{v} = -4 \sin 0 \hat{i} + 4 \cos 0 \hat{j} + 6 \hat{k} = 0\hat{i} + 4\hat{j} + 6\hat{k} \Rightarrow \vec{v} = 4\hat{j} + 6\hat{k}$

At $t = \frac{\pi}{2}$: $\vec{v} = -4 \sin \frac{\pi}{2} \hat{i} + 4 \cos \frac{\pi}{2} \hat{j} + 6 \hat{k} = -4\hat{i} + 0\hat{j} + 6\hat{k} \Rightarrow \vec{v} = -4\hat{i} + 6\hat{k}$

Acceleration: Differentiate \vec{v} w. r. t t .

$$\vec{a} = \frac{d\vec{v}}{dt} = -4 \cos t \hat{i} - 4 \sin t \hat{j} + 0 \hat{k}$$

At $t = 0$: $\vec{a} = -4 \cos 0 \hat{i} - 4 \sin 0 \hat{j} + 0 \hat{k} = -4\hat{i} + 0\hat{j} + 0\hat{k} \Rightarrow \vec{a} = -4\hat{i}$

At $t = \frac{\pi}{2}$: $\vec{a} = -4 \cos \frac{\pi}{2} \hat{i} - 4 \sin \frac{\pi}{2} \hat{j} + 0 \hat{k} = 0\hat{i} - 4\hat{j} + 0\hat{k} \Rightarrow \vec{a} = -4\hat{j}$

Exercise#3.2

Q#01 : If $\vec{f}(t) = (2t + 1)\hat{i} + (3 - 2t^2)\hat{j} + (t^2 - 1)\hat{k}$ & $\vec{g}(t) = (3 + 2t^2)\hat{i} + (3t + 1)\hat{j} + (2t - t^3)\hat{k}$.

Find $\frac{d}{dt} [\vec{f} + \vec{g}]$.

Solution: Given

$$\vec{f}(t) = (2t + 1)\hat{i} + (3 - 2t^2)\hat{j} + (t^2 - 1)\hat{k} \quad \& \quad \vec{g}(t) = (3 + 2t^2)\hat{i} + (3t + 1)\hat{j} + (2t - t^3)\hat{k}$$

Then $\vec{f} + \vec{g} = [(2t + 1)\hat{i} + (3 - 2t^2)\hat{j} + (t^2 - 1)\hat{k}] + [(3 + 2t^2)\hat{i} + (3t + 1)\hat{j} + (2t - t^3)\hat{k}]$

$$= (2t + 1 + 3 + 2t^2)\hat{i} + (3 - 2t^2 + 3t + 1)\hat{j} + (t^2 - 1 + 2t - t^3)\hat{k}$$

$$\vec{f} + \vec{g} = (4 + 2t + 2t^2)\hat{i} + (4 + 3t - 2t^2)\hat{j} + (-1 + 2t + t^2 - t^3)\hat{k}$$

Now taking derivative w. r. t t

$$\frac{d}{dt} [\vec{f} + \vec{g}] = (2 + 4t)\hat{i} + (3 - 4t)\hat{j} + (2 + 2t - 3t^2)\hat{k}$$

Q#02: Find $\frac{d}{dt} [\vec{f} \cdot \vec{g}]$ & $\frac{d}{dt} [\vec{f} \times \vec{g}]$

(i) if $\vec{f}(t) = (3t^2 + 1)\hat{i} + (2t^3 - 1)\hat{j} + (2t^2 + 3t^3)\hat{k}$ & $\vec{g}(t) = t\hat{i} + (t^2 - 2t)\hat{j} + (3t - t^3)\hat{k}$

Solution: Given

$$\vec{f}(t) = (3t^2 + 1)\hat{i} + (2t^3 - 1)\hat{j} + (2t^2 + 3t^3)\hat{k} \quad \& \quad \vec{g}(t) = t\hat{i} + (t^2 - 2t)\hat{j} + (3t - t^3)\hat{k}$$

Then $\vec{f} \cdot \vec{g} = [(3t^2 + 1)\hat{i} + (2t^3 - 1)\hat{j} + (2t^2 + 3t^3)\hat{k}] \cdot [t\hat{i} + (t^2 - 2t)\hat{j} + (3t - t^3)\hat{k}]$

$$= (3t^2 + 1)t + (2t^3 - 1)(t^2 - 2t) + (2t^2 + 3t^3)(3t - t^3)$$

$$= 3t^3 + t + 2t^5 - 4t^4 - t^2 + 2t + 6t^3 - 2t^5 + 9t^4 - 3t^6$$

$$\vec{f} \cdot \vec{g} = 3t - t^2 + 9t^3 + 5t^4 - 3t^6$$

Now taking derivative w. r. t t

$$\frac{d}{dt} [\vec{f} \cdot \vec{g}] = 3 - 2t - 18t^2 + 20t^3 - 18t^5$$

$$\vec{f} \times \vec{g} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 3t^2 + 1 & 2t^3 - 1 & 2t^2 + 3t^3 \\ t & t^2 - 2t & 3t - t^3 \end{vmatrix} = \hat{i} \begin{vmatrix} 2t^3 - 1 & 2t^2 + 3t^3 \\ t^2 - 2t & 3t - t^3 \end{vmatrix} - \hat{j} \begin{vmatrix} 3t^2 + 1 & 2t^2 + 3t^3 \\ t & 3t - t^3 \end{vmatrix} + \hat{k} \begin{vmatrix} 3t^2 + 1 & 2t^3 - 1 \\ t & t^2 - 2t \end{vmatrix}$$

$$= \hat{i} [(2t^3 - 1)(3t - t^3) - (t^2 - 2t)(2t^2 + 3t^3)] - \hat{j} [(3t^2 + 1)(3t - t^3) - (t)(2t^2 + 3t^3)]$$

$$+ \hat{k} [(3t^2 + 1)(t^2 - 2t) - (t)(2t^3 - 1)]$$

$$= \hat{i}[6t^4 - 2t^6 - 3t + t^3 - 2t^4 - 3t^5 + 4t^3 + 6t^4] - \hat{j}[9t^3 - 3t^5 + 3t - t^3 - 2t^3 - 3t^4] + \hat{k}[3t^4 - 6t^3 + t^2 - 2t - 2t^4 + t]$$

$$\vec{f} \times \vec{g} = \hat{i}[-3t + 5t^3 - 10t^4 - 3t^5 - 2t^6] - \hat{j}[3t + 6t^2 - 3t^4 - 3t^5] + \hat{k}[-t + t^2 - 6t^3 + t^4]$$

Now

$$\frac{d}{dt}[\vec{f} \times \vec{g}] = [-3 + 15t^2 - 40t^3 - 15t^4 - 12t^5]\hat{i} - [3 + 12t - 12t^3 - 15t^4]\hat{j} + [-1 + 2t - 18t^2 + 4t^3]\hat{k}$$

(ii) If $\vec{f}(t) = \cos t \hat{i} + \sin t \hat{j} + \hat{k}$ & $\vec{g}(t) = t\hat{i} + (2t - 1)\hat{j} + t^2\hat{k}$.

Solution: Given $\vec{f}(t) = \cos t \hat{i} + \sin t \hat{j} + \hat{k}$ & $\vec{g}(t) = t\hat{i} + (2t - 1)\hat{j} + t^2\hat{k}$

Now $\vec{f} \cdot \vec{g} = [\cos t \hat{i} + \sin t \hat{j} + \hat{k}] \cdot [t\hat{i} + (2t - 1)\hat{j} + t^2\hat{k}] = (\cos t)t + (\sin t)(2t - 1) + (1)(t^2)$

$$\vec{f} \cdot \vec{g} = t \cos t + 2t \sin t - \sin t + t^2$$

Now taking derivative w. r. t t

$$\frac{d}{dt}[\vec{f} \cdot \vec{g}] = -t \sin t + \cos t + 2t \cos t + 2 \sin t - \cos t + 2t = (2 - t) \sin t + 2t \cos t + 2$$

&
$$\vec{f} \times \vec{g} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \cos t & \sin t & 1 \\ t & 2t - 1 & t^2 \end{vmatrix} = \hat{i} \begin{vmatrix} \sin t & 1 \\ 2t - 1 & t^2 \end{vmatrix} - \hat{j} \begin{vmatrix} \cos t & 1 \\ t & t^2 \end{vmatrix} + \hat{k} \begin{vmatrix} \cos t & \sin t \\ t & 2t - 1 \end{vmatrix}$$

$$= \hat{i}[(\sin t)(t^2) - (2t - 1)(1)] - \hat{j}[(\cos t)(t^2) - (t)(1)] + \hat{k}[(\cos t)(2t - 1) - (t)(\sin t)]$$

$$\vec{f} \times \vec{g} = \hat{i}[t^2 \sin t - 2t + 1] - \hat{j}[t^2 \cos t - t] + \hat{k}[2t \cos t - \cos t - t \sin t]$$

Now taking derivative w. r. t t

$$\frac{d}{dt}[\vec{f} \times \vec{g}] = [t^2 \cos t + 2t \sin t - 2]\hat{i} - [-t^2 \sin t + 2t \cos t - 1]\hat{j} + [-2t \sin t + 2 \cos t + \sin t - t \cos t - \sin t]\hat{k}$$

$$\frac{d}{dt}[\vec{f} \times \vec{g}] = [t^2 \cos t + 2t \sin t - 2]\hat{i} - [-t^2 \sin t + 2t \cos t - 1]\hat{j} + [-2t \sin t + 2 \cos t - t \cos t]\hat{k}$$

Q#03: (i) If \vec{r} is position vector of moving point then show that $\vec{r} \cdot \frac{d\vec{r}}{dt} = r \frac{dr}{dt}$ here $|\vec{r}| = r$.

(ii) Interpret the relation $\vec{r} \cdot \frac{d\vec{r}}{dt} = 0$ & $\vec{r} \times \frac{d\vec{r}}{dt} = 0$.

(i) If \vec{r} is position vector of moving point then show that $\vec{r} \cdot \frac{d\vec{r}}{dt} = r \frac{dr}{dt}$ here $|\vec{r}| = r$.

Solution: If \vec{r} is position vector of moving point. Then

$$\vec{r} \cdot \vec{r} = r^2$$

Differentiate w.r.t t
$$\frac{d}{dt}[\vec{r} \cdot \vec{r}] = \frac{d}{dt} r^2$$

$$\frac{d\vec{r}}{dt} \cdot \vec{r} + \vec{r} \cdot \frac{d\vec{r}}{dt} = 2r \frac{dr}{dt}$$

$$2 \vec{r} \cdot \frac{d\vec{r}}{dt} = 2r \frac{dr}{dt}$$

$$\therefore \vec{r} \cdot \frac{d\vec{r}}{dt} = \frac{dr}{dt} \cdot r$$

$$\vec{r} \cdot \frac{d\vec{r}}{dt} = r \frac{dr}{dt}$$

Hence proved.

(ii) Interpret the relation $\vec{r} \cdot \frac{d\vec{r}}{dt} = 0$ & $\vec{r} \times \frac{d\vec{r}}{dt} = 0$.

(a) If \vec{r} & $\frac{d\vec{r}}{dt}$ are perpendicular. ($\theta = 90^\circ$) Then

As $\vec{r} \cdot \frac{d\vec{r}}{dt} = |\vec{r}| \left| \frac{d\vec{r}}{dt} \right| \cos 90^\circ = |\vec{r}| \left| \frac{d\vec{r}}{dt} \right| (0)$ Because $\cos 90^\circ = 0$

$$\vec{r} \cdot \frac{d\vec{r}}{dt} = 0$$

(b) If \vec{r} & $\frac{d\vec{r}}{dt}$ are parallel. ($\theta = 0^\circ$) Then

As $\vec{r} \times \frac{d\vec{r}}{dt} = |\vec{r}| \left| \frac{d\vec{r}}{dt} \right| \sin 0^\circ = |\vec{r}| \left| \frac{d\vec{r}}{dt} \right| (0)$ Because $\sin 0^\circ = 0$

$$\vec{r} \times \frac{d\vec{r}}{dt} = 0$$

Q#04: If $\vec{r} = \cos 5t \hat{i} + \sin 5t \hat{j}$. Then show that $\vec{r} \times \frac{d\vec{r}}{dt} = 5\hat{k}$.

Solution: Given vector function $\vec{r} = \cos 5t \hat{i} + \sin 5t \hat{j}$ Then $\frac{d\vec{r}}{dt} = -5 \sin 5t \hat{i} + 5 \cos 5t \hat{j}$

Now $\vec{r} \times \frac{d\vec{r}}{dt} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \cos 5t & \sin 5t & 0 \\ -5 \sin 5t & 5 \cos 5t & 0 \end{vmatrix} = \hat{k} \begin{vmatrix} \cos 5t & \sin 5t \\ -5 \sin 5t & 5 \cos 5t \end{vmatrix}$ \therefore Expanding by C_3

$$= \hat{k}[(\cos 5t)(5 \cos 5t) - (-5 \sin 5t)(\sin 5t)]$$

$$= 5\hat{k}[\cos^2 5t + \sin^2 5t]$$

Hence proved $\vec{r} \times \frac{d\vec{r}}{dt} = 5\hat{k}$.

Q#05: If $\vec{f}(t) = \vec{a} \cos \omega t + \vec{b} \sin \omega t$ then show that $\vec{f} \times \vec{f}' = \omega (\vec{a} \times \vec{b})$.

Solution: Given

$$\vec{f}(t) = \vec{a} \cos \omega t + \vec{b} \sin \omega t$$

Then $\vec{f}'(t) = -\vec{a} \omega \sin \omega t + \vec{b} \omega \cos \omega t$

Now

$$\vec{f} \times \vec{f}' = (\vec{a} \cos \omega t + \vec{b} \sin \omega t) \times (-\vec{a} \omega \sin \omega t + \vec{b} \omega \cos \omega t)$$

$$= -(\vec{a} \times \vec{a}) \omega \cos \omega t \sin \omega t + (\vec{a} \times \vec{b}) \omega \cos^2 \omega t + (-\vec{b} \times \vec{a}) \omega \sin^2 \omega t + (\vec{b} \times \vec{b}) \omega \cos \omega t \sin \omega t$$

$$= 0 + (\vec{a} \times \vec{b}) \omega \cos^2 \omega t + (\vec{a} \times \vec{b}) \omega \sin^2 \omega t + 0$$

$$\therefore \vec{a} \times \vec{a} = 0 \text{ \& } \vec{b} \times \vec{b} = 0$$

$$= \omega (\vec{a} \times \vec{b}) [\cos^2 \omega t + \sin^2 \omega t]$$

$$\therefore \vec{a} \times \vec{b} = -\vec{b} \times \vec{a} \quad \vec{f} \times$$

$$\vec{f}' = \omega (\vec{a} \times \vec{b})$$

Hence proved

Q#06: If \hat{r} is a unit vector then prove that $|\hat{r} \times \frac{d\hat{r}}{dt}| = \left| \frac{d\hat{r}}{dt} \right|$

Solution: If \hat{r} is a unit vector.

Then $|\hat{r} \times \frac{d\hat{r}}{dt}| = |\hat{r}| \left| \frac{d\hat{r}}{dt} \right| \sin \theta$

We know that \hat{r} & $\frac{d\hat{r}}{dt}$ are perpendicular vectors. Then $\theta = 90^\circ$

$$|\hat{r} \times \frac{d\hat{r}}{dt}| = |\hat{r}| \left| \frac{d\hat{r}}{dt} \right| \sin 90^\circ$$

$$|\hat{r} \times \frac{d\hat{r}}{dt}| = (1) \left| \frac{d\hat{r}}{dt} \right| \quad (I) \quad \therefore |\hat{r}| = 1 \text{ \& } \sin 90^\circ = 1$$

$$|\hat{r} \times \frac{d\hat{r}}{dt}| = \left| \frac{d\hat{r}}{dt} \right|$$

Hence proved.

Q#07: If $\vec{r} = \vec{a} \sin \omega t + \vec{b} \cos \omega t + \frac{\vec{c}}{\omega^2} t \sin \omega t$ then prove that $\frac{d^2\vec{r}}{dt^2} + \omega^2 \vec{r} = \frac{2\vec{c}}{\omega} \cos \omega t$.

Where $\vec{a}, \vec{b}, \vec{c}$ are constant vectors and ω is a scalar.

Solution: Given vector function is $\vec{r} = \vec{a} \sin \omega t + \vec{b} \cos \omega t + \frac{\vec{c}}{\omega^2} t \sin \omega t$ -----(i)

Then $\frac{d\vec{r}}{dt} = \vec{a} \omega \cos \omega t - \vec{b} \omega \sin \omega t + \frac{\vec{c}}{\omega^2} \omega t \cos \omega t + \frac{\vec{c}}{\omega^2} \sin \omega t$

$$\frac{d\vec{r}}{dt} = \vec{a} \omega \cos \omega t - \vec{b} \omega \sin \omega t + \frac{\vec{c}}{\omega} t \cos \omega t + \frac{\vec{c}}{\omega^2} \sin \omega t$$

& $\frac{d^2\vec{r}}{dt^2} = -\vec{a} \omega^2 \sin \omega t - \vec{b} \omega^2 \cos \omega t - \frac{\vec{c}}{\omega} \omega t \sin \omega t + \frac{\vec{c}}{\omega} \cos \omega t + \frac{\vec{c}}{\omega^2} \omega \cos \omega t$

$$\frac{d^2\vec{r}}{dt^2} = -\vec{a} \omega^2 \sin \omega t - \vec{b} \omega^2 \cos \omega t - \vec{c} t \sin \omega t + \frac{\vec{c}}{\omega} \cos \omega t + \frac{\vec{c}}{\omega} \cos \omega t$$

$$\frac{d^2\vec{r}}{dt^2} = -\omega^2 [\vec{a} \sin \omega t + \vec{b} \cos \omega t + \frac{\vec{c}}{\omega^2} t \sin \omega t] + 2 \frac{\vec{c}}{\omega} \cos \omega t$$

$$\frac{d^2\vec{r}}{dt^2} = -\omega^2 \vec{r} + \frac{2\vec{c}}{\omega} \cos \omega t \quad \therefore \text{From (i)}$$

$$\frac{d^2\vec{r}}{dt^2} + \omega^2 \vec{r} = \frac{2\vec{c}}{\omega} \cos \omega t$$

Hence proved.

Q#08: If $\vec{r} = a \cos t \hat{i} + a \sin t \hat{j} + a t \tan \alpha \hat{k}$ then show that

(i) $\left[\frac{d\vec{r}}{dt} \quad \frac{d^2\vec{r}}{dt^2} \quad \frac{d^3\vec{r}}{dt^3} \right] = a^3 \tan \alpha$ (ii) $\left| \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} \right| = a^2 \sec \alpha$

Solution: Given vector function is $\vec{r} = a \cos t \hat{i} + a \sin t \hat{j} + a t \tan \alpha \hat{k}$

Then $\frac{d\vec{r}}{dt} = -a \sin t \hat{i} + a \cos t \hat{j} + a \tan \alpha \hat{k}$;

$$\frac{d^2\vec{r}}{dt^2} = -a \cos t \hat{i} - a \sin t \hat{j} + 0 \hat{k}$$

& $\frac{d^3\vec{r}}{dt^3} = a \sin t \hat{i} - a \cos t \hat{j} + 0 \hat{k}$

(i) Now taking L.H.S

$$\left[\frac{d\vec{r}}{dt} \quad \frac{d^2\vec{r}}{dt^2} \quad \frac{d^3\vec{r}}{dt^3} \right] = \frac{d\vec{r}}{dt} \cdot \left(\frac{d^2\vec{r}}{dt^2} \times \frac{d^3\vec{r}}{dt^3} \right) = \begin{vmatrix} -a \sin t & a \cos t & a \tan \alpha \\ -a \cos t & -a \sin t & 0 \\ a \sin t & -a \cos t & 0 \end{vmatrix} = a \tan \alpha \begin{vmatrix} -a \cos t & -a \sin t \\ a \sin t & -a \cos t \end{vmatrix} \therefore \text{Expanding by } C_3$$

$$= a \tan \alpha [(-a \cos t)(-a \cos t) - (a \sin t)(- \sin t)] = a \tan \alpha [a^2 \cos^2 t + a^2 \sin^2 t]$$

$$\left[\frac{d\vec{r}}{dt} \quad \frac{d^2\vec{r}}{dt^2} \quad \frac{d^3\vec{r}}{dt^3} \right] = a^3 \tan \alpha \quad \text{Hence proved.}$$

(ii) Now Taking cross product

$$\frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -a \sin t & a \cos t & a \tan \alpha \\ -a \cos t & -a \sin t & 0 \end{vmatrix} = \hat{i} \begin{vmatrix} a \cos t & a \tan \alpha \\ -a \sin t & 0 \end{vmatrix} - \hat{j} \begin{vmatrix} -a \sin t & a \tan \alpha \\ -a \cos t & 0 \end{vmatrix} + \hat{k} \begin{vmatrix} -a \sin t & a \cos t \\ -a \cos t & -a \sin t \end{vmatrix}$$

$$= \hat{i} [(a \cos t)(0) - (-a \sin t)(a \tan \alpha)] - \hat{j} [(-a \sin t)(0) - (-a \cos t)(a \tan \alpha)]$$

$$+ \hat{k} [(-a \sin t)(-a \sin t) - (-a \cos t)(a \cos t)]$$

$$= \hat{i} [0 + a^2 \sin t \tan \alpha] - \hat{j} [0 + a^2 \cos t \tan \alpha] + \hat{k} [a^2 \sin^2 t + a^2 \cos^2 t]$$

$$= \hat{i} [a^2 \sin t \tan \alpha] - \hat{j} [a^2 \cos t \tan \alpha] + \hat{k} a^2 [\sin^2 t + \cos^2 t]$$

$$\frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} = [a^2 \sin t \tan \alpha] \hat{i} - [a^2 \cos t \tan \alpha] \hat{j} + a^2 \hat{k}$$

Taking magnitude $\left| \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} \right| = \sqrt{(a^2 \sin t \tan \alpha)^2 + (a^2 \cos t \tan \alpha)^2 + (a^2)^2}$

$$= \sqrt{[(a^2)^2] [\sin^2 t \tan^2 \alpha + \cos^2 t \tan^2 \alpha + 1]}$$

$$= \sqrt{[(a^2)^2] [(\sin^2 t + \cos^2 t) \tan^2 \alpha + 1]} = \sqrt{(a^2)^2 [\tan^2 \alpha + 1]}$$

$$= \sqrt{(a^2)^2 [\sec^2 \alpha]} = \sqrt{(a^2 \sec \alpha)^2}$$

$$\left| \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} \right| = a^2 \sec \alpha \quad \text{Hence proved}$$

Q#09: If $\vec{r} = \cos 2t \vec{a} + \sin 2t \vec{b}$. Where \vec{a} & \vec{b} are constant vectors. Show that

(i) $\frac{d^2\vec{r}}{dt^2} + 4\vec{r} = 0$ (ii) $\vec{r} \times \frac{d\vec{r}}{dt} = 2(\vec{a} \times \vec{b})$

Solution: Given vector $\vec{r} = \cos 2t \vec{a} + \sin 2t \vec{b}$ -----(i)

Then $\frac{d\vec{r}}{dt} = -2 \sin 2t \vec{a} + 2 \cos 2t \vec{b}$

(i) $\frac{d^2\vec{r}}{dt^2} = -4 \cos 2t \vec{a} - 4 \sin 2t \vec{b}$

$\frac{d^2\vec{r}}{dt^2} = -4 [\cos 2t \vec{a} + \sin 2t \vec{b}]$

$\frac{d^2\vec{r}}{dt^2} = -4\vec{r}$ \therefore From (i)

$\frac{d^2\vec{r}}{dt^2} + 4\vec{r} = 0$ **Hence proved .**

(ii) Now $\vec{r} \times \frac{d\vec{r}}{dt} = (\cos 2t \vec{a} + \sin 2t \vec{b}) \times (-2 \sin 2t \vec{a} + 2 \cos 2t \vec{b})$
 $= -2 \cos 2t \sin 2t (\vec{a} \times \vec{a}) + 2 \cos^2 2t (\vec{a} \times \vec{b}) + 2 \sin^2 2t (-\vec{b} \times \vec{a})$
 $+ 2 \cos 2t \sin 2t (\vec{b} \times \vec{b})$ $\therefore \vec{a} \times \vec{a} = 0$ & $\vec{b} \times \vec{b} = 0$
 $= 0 + 2 \cos^2 2t (\vec{a} \times \vec{b}) + 2 \sin^2 2t (\vec{a} \times \vec{b}) + 0$ $\therefore \vec{a} \times \vec{b} = -\vec{b} \times \vec{a}$
 $= 2 (\vec{a} \times \vec{b}) [\cos^2 2t + \sin^2 2t]$

$\vec{r} \times \frac{d\vec{r}}{dt} = 2 (\vec{a} \times \vec{b})$ **Hence proved .**

Q#10: If $\vec{r} = \vec{a} e^{3t} + \vec{b} e^{-3t}$. Where \vec{a} & \vec{b} are constant vectors. Show that $\frac{d^2\vec{r}}{dt^2} - 9\vec{r} = 0$

Solution: Given vector function $\vec{r} = \vec{a} e^{3t} + \vec{b} e^{-3t}$ -----(i)

Then $\frac{d\vec{r}}{dt} = 3\vec{a} e^{3t} - 3\vec{b} e^{-3t}$

& $\frac{d^2\vec{r}}{dt^2} = 9\vec{a} e^{3t} + 9\vec{b} e^{-3t}$

$\frac{d^2\vec{r}}{dt^2} = 9[\vec{a} e^{3t} + \vec{b} e^{-3t}]$

$\frac{d^2\vec{r}}{dt^2} = 9\vec{r}$ \therefore **From (i)**

$\frac{d^2\vec{r}}{dt^2} - 9\vec{r} = 0$ **Hence proved .**

Q#11: If $\vec{r} = \vec{a} e^{2t} + \vec{b} e^{3t}$. Where \vec{a} & \vec{b} are constant vectors. Show that $\frac{d^2\vec{r}}{dt^2} - 5\frac{d\vec{r}}{dt} + 6\vec{r} = 0$

Solution: Given vector function $\vec{r} = \vec{a} e^{2t} + \vec{b} e^{3t}$ ------(i)

Then $\frac{d\vec{r}}{dt} = 2\vec{a} e^{2t} + 3\vec{b} e^{3t}$

& $\frac{d^2\vec{r}}{dt^2} = 4\vec{a} e^{2t} + 9\vec{b} e^{3t}$

Now $\frac{d^2\vec{r}}{dt^2} - 5\frac{d\vec{r}}{dt} + 6\vec{r} = 4\vec{a} e^{2t} + 9\vec{b} e^{3t} - 5[2\vec{a} e^{2t} + 3\vec{b} e^{3t}] + 6[\vec{a} e^{2t} + \vec{b} e^{3t}]$

$$= 4\vec{a} e^{2t} + 9\vec{b} e^{3t} - 10\vec{a} e^{2t} - 15\vec{b} e^{3t} + 6\vec{a} e^{2t} + 6\vec{b} e^{3t}$$

$$\frac{d^2\vec{r}}{dt^2} - 5\frac{d\vec{r}}{dt} + 6\vec{r} = 0$$

Hence proved .

Q#12: (i) If $\vec{r} = a \cos t \hat{i} + a \sin t \hat{j} + b \hat{k}$ then show that

(a) $\left| \frac{d\vec{r}}{dt} \right|^2 = a^2 + b^2$ (b) $\left| \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} \right|^2 = a^2 (a^2 + b^2)$ (c) $\left[\frac{d\vec{r}}{dt} \cdot \frac{d^2\vec{r}}{dt^2} \cdot \frac{d^3\vec{r}}{dt^3} \right] = a^2 b$

(ii) If $\vec{r} = \vec{c}_1 e^{\omega t} + \vec{c}_2 e^{-\omega t}$. Where \vec{c}_1 & \vec{c}_2 are constant vectors . Show that $\frac{d^2\vec{r}}{dt^2} - \omega^2\vec{r} = 0$

(i) If $\vec{r} = a \cos t \hat{i} + a \sin t \hat{j} + b \hat{k}$ then show that

Solution: Given vector function $\vec{r} = a \cos t \hat{i} + a \sin t \hat{j} + b \hat{k}$

Then $\frac{d\vec{r}}{dt} = -a \sin t \hat{i} + a \cos t \hat{j} + b \hat{k}$

& $\frac{d^2\vec{r}}{dt^2} = -a \cos t \hat{i} - a \sin t \hat{j} + 0 \hat{k}$

$$\frac{d^3\vec{r}}{dt^3} = a \sin t \hat{i} - a \cos t \hat{j} + 0 \hat{k}$$

(a) $\left| \frac{d\vec{r}}{dt} \right| = \sqrt{(a \sin t)^2 + (-a \cos t)^2 + (b)^2} = \sqrt{a^2 \sin^2 t + a^2 \cos^2 t + b^2} = \sqrt{a^2 [\sin^2 t + \cos^2 t] + b^2}$

$$\left| \frac{d\vec{r}}{dt} \right| = \sqrt{a^2 + b^2}$$

Taking square on both sides

$$\left| \frac{d\vec{r}}{dt} \right|^2 = a^2 + b^2$$

Hence proved

$$\begin{aligned}
 (b) \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -a \sin t & a \cos t & b \\ -a \cos t & -a \sin t & 0 \end{vmatrix} = \hat{i} \begin{vmatrix} a \cos t & b \\ -a \sin t & 0 \end{vmatrix} - \hat{j} \begin{vmatrix} -a \sin t & b \\ -a \cos t & 0 \end{vmatrix} + \hat{k} \begin{vmatrix} -a \sin t & a \cos t \\ -a \cos t & -a \sin t \end{vmatrix} \\
 &= \hat{i} [(a \cos t)(0) - (-a \sin t)(b)] - \hat{j} [(-a \sin t)(0) - (-a \cos t)(b)] \\
 &\quad + \hat{k} [(-a \sin t)(-a \sin t) - (-a \cos t)(a \cos t)] \\
 &= \hat{i} [0 + ab \sin t] - \hat{j} [0 + ab \cos t] + \hat{k} [a^2 \sin^2 t + a^2 \cos^2 t] \\
 &= \hat{i} [ab \sin t] - \hat{j} [ab \cos t] + \hat{k} a^2 [\sin^2 t + \cos^2 t]
 \end{aligned}$$

$$\frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} = [ab \sin t] \hat{i} - [ab \cos t] \hat{j} + a^2 \hat{k}$$

Taking magnitude $\left| \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} \right| = \sqrt{(ab \sin t)^2 + (ab \cos t)^2 + (a^2)^2} = \sqrt{[a^2 b^2] [\sin^2 t + \cos^2 t] + a^4}$

$$\left| \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} \right| = \sqrt{a^2 b^2 + a^4} = \sqrt{a^2 (b^2 + a^2)}$$

Taking square on both sides $\left| \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} \right|^2 = a^2 (a^2 + b^2)$

$$\begin{aligned}
 (c) \left[\frac{d\vec{r}}{dt} \quad \frac{d^2\vec{r}}{dt^2} \quad \frac{d^3\vec{r}}{dt^3} \right] &= \frac{d\vec{r}}{dt} \cdot \left(\frac{d^2\vec{r}}{dt^2} \times \frac{d^3\vec{r}}{dt^3} \right) = \begin{vmatrix} -a \sin t & a \cos t & b \\ -a \cos t & -a \sin t & 0 \\ a \sin t & -a \cos t & 0 \end{vmatrix} = b \begin{vmatrix} -a \cos t & -a \sin t \\ a \sin t & -a \cos t \end{vmatrix} \therefore \text{Expanding by } C_3 \\
 &= b [(-a \cos t)(-a \cos t) - (a \sin t)(- \sin t)] = b [a^2 \cos^2 t + a^2 \sin^2 t]
 \end{aligned}$$

$$\left[\frac{d\vec{r}}{dt} \quad \frac{d^2\vec{r}}{dt^2} \quad \frac{d^3\vec{r}}{dt^3} \right] = a^2 b \quad \text{Hence proved.}$$

(ii) If $\vec{r} = \vec{c}_1 e^{\omega t} + \vec{c}_2 e^{-\omega t}$. Where \vec{c}_1 & \vec{c}_2 are constant vectors. Show that $\frac{d^2\vec{r}}{dt^2} - \omega^2 \vec{r} = 0$

Solution: Given vector function $\vec{r} = \vec{c}_1 e^{\omega t} + \vec{c}_2 e^{-\omega t}$ ----- (i)

Then $\frac{d\vec{r}}{dt} = \omega \vec{c}_1 e^{\omega t} - \omega \vec{c}_2 e^{-\omega t}$

& $\frac{d^2\vec{r}}{dt^2} = \omega^2 \vec{c}_1 e^{\omega t} + \omega^2 \vec{c}_2 e^{-\omega t}$

$$\frac{d^2\vec{r}}{dt^2} = \omega^2 [\vec{c}_1 e^{\omega t} + \vec{c}_2 e^{-\omega t}]$$

$$\frac{d^2\vec{r}}{dt^2} = \omega^2 \vec{r} \quad \therefore \text{From (i)}$$

$$\frac{d^2\vec{r}}{dt^2} - \omega^2 \vec{r} = 0$$

Hence proved.

Q#13: If $\vec{f}(t)$ is a vector function. Show that $\frac{d}{dt}(\vec{f} \times \vec{f}') = \vec{f} \times \vec{f}''$

Solution: If $\vec{f}(t)$ is a vector function. Then

$$\begin{aligned} \frac{d}{dt}(\vec{f} \times \vec{f}') &= \frac{d}{dt}\vec{f} \times \vec{f}' + \vec{f} \times \frac{d}{dt}\vec{f}' \\ &= \vec{f}' \times \vec{f}' + \vec{f} \times \vec{f}'' \\ &= \mathbf{0} + \vec{f} \times \vec{f}'' \qquad \qquad \qquad \therefore \vec{f}' \times \vec{f}' = 0 \\ \frac{d}{dt}(\vec{f} \times \vec{f}') &= \vec{f} \times \vec{f}'' \qquad \text{Hence proved.} \end{aligned}$$

Q#14: If $\vec{r} = t^3\hat{i} + \left(2t^3 - \frac{1}{5t^2}\right)\hat{j}$. Where n is a constant. show that $\vec{r} \times \frac{d\vec{r}}{dt} = \hat{k}$.

Solution: Given vector function is

$$\vec{r} = t^3\hat{i} + \left(2t^3 - \frac{1}{5t^2}\right)\hat{j}$$

Differentiate w. r. t t

$$\frac{d\vec{r}}{dt} = 3t^2\hat{i} + \left(6t^2 - \frac{-2}{5t^3}\right)\hat{j} = 3t^2\hat{i} + \left(6t^2 + \frac{2}{5t^3}\right)\hat{j}$$

Now $\vec{r} \times \frac{d\vec{r}}{dt} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ t^3 & 2 - \frac{1}{5t^2} & 0 \\ 3t^2 & 6t^2 + \frac{2}{5t^3} & 0 \end{vmatrix} = 0\hat{i} - 0\hat{j} + \hat{k} \begin{vmatrix} t^3 & 2t^3 - \frac{1}{5t^2} \\ 3t^2 & 6t^2 + \frac{2}{5t^3} \end{vmatrix}$

$$\begin{aligned} &= \hat{k} \left[(t^3) \left(6t^2 + \frac{2}{5t^3}\right) - (3t^2) \left(2t^3 - \frac{1}{5t^2}\right) \right] \\ &= \hat{k} \left[6t^5 + \frac{2}{5} - 6t^5 + \frac{3}{5} \right] \\ &= \hat{k} \left[\frac{2}{5} + \frac{3}{5} \right] = \hat{k} \left[\frac{2+3}{5} \right] = \hat{k} \left[\frac{5}{5} \right] \\ &= \hat{k} [1] \end{aligned}$$

$\vec{r} \times \frac{d\vec{r}}{dt} = \hat{k}$ **Hence proved.**

Q#15: If $\vec{a} = 5t^2\hat{i} + t\hat{j} - t^3\hat{k}$ & $\vec{b} = \sin t\hat{i} - \cos t\hat{j}$ (i) $\frac{d}{dt}(\vec{a} \cdot \vec{b})$ (ii) $\frac{d}{dt}(\vec{a} \cdot \vec{a})$ (iii) $\frac{d}{dt}(\vec{a} \times \vec{b})$

Solution: Given vectors $\vec{a} = 5t^2\hat{i} + t\hat{j} - t^3\hat{k}$ & $\vec{b} = \sin t\hat{i} - \cos t\hat{j}$

(i) $\vec{a} \cdot \vec{b} = (5t^2\hat{i} + t\hat{j} - t^3\hat{k}) \cdot (\sin t\hat{i} - \cos t\hat{j} + 0\hat{k}) = 5t^2 \sin t - t \cos t - t^3 (0)$

$$\vec{a} \cdot \vec{b} = 5t^2 \sin t - t \cos t$$

Now $\frac{d}{dt}(\vec{a} \cdot \vec{b}) = 5[t^2 \cos t + 2t \sin t] - [-t \sin t + \cos t] = 5t^2 \cos t + 10t \sin t + t \sin t - \cos t$
 $= (5t^2 - 1) \cos t + 11 t \sin t$

(ii) $\vec{a} \cdot \vec{a} = (5t^2\hat{i} + t\hat{j} - t^3\hat{k}) \cdot (5t^2\hat{i} + t\hat{j} - t^3\hat{k}) = (5t^2)(5t^2) + (t)(t) + (-t^3)(-t^3) = 25t^4 + t^2 + t^6$

$$\vec{a} \cdot \vec{a} = t^6 + 25t^4 + t^2$$

Differentiate w.r. t t

$$\frac{d}{dt}(\vec{a} \cdot \vec{a}) = 6t^5 + 100t^3 + 2t$$

(iii) $\vec{a} \times \vec{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 5t^2 & t & -t^3 \\ \sin t & -\cos t & 0 \end{vmatrix} = \hat{i} \begin{vmatrix} t & -t^3 \\ -\cos t & 0 \end{vmatrix} - \hat{j} \begin{vmatrix} 5t^2 & -t^3 \\ \sin t & 0 \end{vmatrix} + \hat{k} \begin{vmatrix} 5t^2 & t \\ \sin t & -\cos t \end{vmatrix}$
 $= \hat{i}[(t)(0) - (\cos t)(-t^3)] - \hat{j}[(5t^2)(0) - (\sin t)(-t^3)] + \hat{k}[5t^2(-\cos t) - (\sin t)(t)]$
 $= \hat{i}[0 - t^3 \cos t] - \hat{j}[0 + t^3 \sin t] + \hat{k}[-5t^2 \cos t - t \sin t]$
 $= -\hat{i}[t^3 \cos t] - \hat{j}[t^3 \sin t] + \hat{k}[-5t^2 \cos t - t \sin t]$

Differentiate w.r. t t

$$\frac{d}{dt}(\vec{a} \times \vec{b}) = -\hat{i}[-t^3 \sin t + 3t^2 \cos t] - \hat{j}[t^3 \cos t + 3t^2 \sin t] + \hat{k}[-5(-t^2 \sin t + 2t \cos t) - (t \cos t + \sin t)]$$

 $= \hat{i}[t^3 \sin t - 3t^2 \cos t] - \hat{j}[t^3 \cos t + 3t^2 \sin t] + \hat{k}[5t^2 \sin t - 10t \cos t - t \cos t - \sin t]$
 $= \hat{i}[t^3 \sin t - 3t^2 \cos t] - \hat{j}[t^3 \cos t + 3t^2 \sin t] + \hat{k}[(5t^2 - 1) \sin t - 11 t \cos t]$

Q#16: If $\vec{f}(t)$ is a vector function. Show that $\frac{d}{dt}[\vec{f} \cdot (\vec{f}' \times \vec{f}'')] = \vec{f} \cdot (\vec{f}'' \times \vec{f}''')$

Solution: If $\vec{f}(t)$ is a vector function. Then

$$\frac{d}{dt}[\vec{f} \cdot (\vec{f}' \times \vec{f}'')] = \frac{d}{dt} \vec{f} \cdot (\vec{f}' \times \vec{f}'') + [\vec{f} \cdot (\frac{d}{dt} \vec{f}' \times \vec{f}'')] + \vec{f} \cdot (\vec{f}' \times \frac{d}{dt} \vec{f}'')$$

 $= \vec{f}' \cdot (\vec{f}' \times \vec{f}'') + \vec{f} \cdot (\vec{f}'' \times \vec{f}''') + \vec{f} \cdot (\vec{f}'' \times \vec{f}''')$
 $= 0 + 0 + \vec{f} \cdot (\vec{f}'' \times \vec{f}''')$

$$\frac{d}{dt}[\vec{f} \cdot (\vec{f}' \times \vec{f}'')] = \vec{f} \cdot (\vec{f}'' \times \vec{f}''') \quad \text{Hence proved.}$$

Q#17: Show that $\frac{d}{dt} \left[\vec{a} \times \frac{d\vec{b}}{dt} - \frac{d\vec{a}}{dt} \times \vec{b} \right] = \vec{a} \times \frac{d^2\vec{b}}{dt^2} - \frac{d^2\vec{a}}{dt^2} \times \vec{b}$

Solution: Let

$$\begin{aligned} \frac{d}{dt} \left[\vec{a} \times \frac{d\vec{b}}{dt} - \frac{d\vec{a}}{dt} \times \vec{b} \right] &= \frac{d}{dt} \left[\vec{a} \times \frac{d\vec{b}}{dt} \right] - \frac{d}{dt} \left[\frac{d\vec{a}}{dt} \times \vec{b} \right] \\ &= \left[\frac{d\vec{a}}{dt} \times \frac{d\vec{b}}{dt} + \vec{a} \times \frac{d}{dt} \left(\frac{d\vec{b}}{dt} \right) \right] - \left[\frac{d}{dt} \left(\frac{d\vec{a}}{dt} \right) \times \vec{b} + \frac{d\vec{a}}{dt} \times \frac{d\vec{b}}{dt} \right] \\ &= \frac{d\vec{a}}{dt} \times \frac{d\vec{b}}{dt} + \vec{a} \times \frac{d^2\vec{b}}{dt^2} - \frac{d^2\vec{a}}{dt^2} \times \vec{b} - \frac{d\vec{a}}{dt} \times \frac{d\vec{b}}{dt} \\ \frac{d}{dt} \left[\vec{a} \times \frac{d\vec{b}}{dt} - \frac{d\vec{a}}{dt} \times \vec{b} \right] &= \vec{a} \times \frac{d^2\vec{b}}{dt^2} - \frac{d^2\vec{a}}{dt^2} \times \vec{b} \quad \text{Hence proved.} \end{aligned}$$

Q#18: If $\hat{r}(t)$ is a unit vector then show that $\hat{r} \cdot \left(\hat{r} \times \frac{d^2\hat{r}}{dt^2} \right) + \left(\frac{d\hat{r}}{dt} \right)^2 = 1$.

Solution: If $\hat{r}(t)$ is a unit vector. Then

$$\begin{aligned} \hat{r} \cdot \hat{r} &= |\hat{r}|^2 \\ \hat{r} \cdot \hat{r} &= 1 \quad \text{-----(i)} \quad \therefore |\hat{r}| = 1 \end{aligned}$$

Differentiate (i) w. r. t t

$$\begin{aligned} \frac{d}{dt} (\hat{r} \cdot \hat{r}) &= \frac{d}{dt} (1) \\ \frac{d\hat{r}}{dt} \cdot \hat{r} + \hat{r} \cdot \frac{d\hat{r}}{dt} &= 0 \quad \therefore \frac{d\hat{r}}{dt} \cdot \hat{r} = \hat{r} \cdot \frac{d\hat{r}}{dt} \end{aligned}$$

$$\begin{aligned} 2 \hat{r} \cdot \frac{d\hat{r}}{dt} &= 0 \\ \hat{r} \cdot \frac{d\hat{r}}{dt} &= 0 \end{aligned}$$

Again differentiate w.r. t t

$$\begin{aligned} \frac{d}{dt} \left(\hat{r} \cdot \frac{d\hat{r}}{dt} \right) &= \frac{d}{dt} (0) \\ \hat{r} \cdot \frac{d^2\hat{r}}{dt^2} + \frac{d\hat{r}}{dt} \cdot \frac{d\hat{r}}{dt} &= 0 \quad \therefore \frac{d\hat{r}}{dt} \cdot \frac{d\hat{r}}{dt} = \left(\frac{d\hat{r}}{dt} \right)^2 \end{aligned}$$

$$\hat{r} \cdot \frac{d^2\hat{r}}{dt^2} + \left(\frac{d\hat{r}}{dt} \right)^2 = 0 \text{-----(ii)}$$

Adding (i) & (ii)

$$\hat{r} \cdot \hat{r} + \hat{r} \cdot \frac{d^2\hat{r}}{dt^2} + \left(\frac{d\hat{r}}{dt} \right)^2 = 1 + 0$$

$$\hat{r} \cdot \left(\hat{r} \cdot \frac{d^2\hat{r}}{dt^2} \right) + \left(\frac{d\hat{r}}{dt} \right)^2 = 1 \quad \text{Hence proved.}$$

Q#19: If \hat{a} is a unit vector in the direction of \vec{a} . Then prove that $\hat{a} \times \frac{d\hat{a}}{dt} = \frac{1}{|\vec{a}|^2} \vec{a} \times \frac{d\vec{a}}{dt}$

Solution: If \hat{a} is a unit vector in the direction of \vec{a} . Then

$$\hat{a} = \frac{\vec{a}}{|\vec{a}|} \text{-----(i)}$$

Differentiate (i) w. r. t t $\frac{d\hat{a}}{dt} = \frac{1}{|\vec{a}|} \frac{d\vec{a}}{dt} \text{-----(ii)}$

Taking cross product of (i) & (ii)

$$\hat{a} \times \frac{d\hat{a}}{dt} = \frac{\vec{a}}{|\vec{a}|} \times \frac{1}{|\vec{a}|} \frac{d\vec{a}}{dt}$$

$$\hat{a} \times \frac{d\hat{a}}{dt} = \frac{1}{|\vec{a}|^2} \vec{a} \times \frac{d\vec{a}}{dt}$$

Hence proved.

Q#20: If $\vec{r}(t)$ is a vector of magnitude 2. then show that $\vec{r} \cdot \left(\vec{r} \times \frac{d^2\vec{r}}{dt^2} \right) + \left(\frac{d\vec{r}}{dt} \right)^2 = 1$.

Solution: If $\vec{r}(t)$ is a vector of magnitude 2. $\{ |\vec{r}| = 2 \}$

. Then

$$\vec{r} \cdot \vec{r} = |\vec{r}|^2$$

$$\vec{r} \cdot \vec{r} = 4 \text{-----(i)} \quad \therefore |\vec{r}|^2 = 4$$

Differentiate (i) w. r. t t

$$\frac{d}{dt} (\vec{r} \cdot \vec{r}) = \frac{d}{dt} (4)$$

$$\frac{d\vec{r}}{dt} \cdot \vec{r} + \vec{r} \cdot \frac{d\vec{r}}{dt} = 0 \quad \therefore \frac{d\vec{r}}{dt} \cdot \vec{r} = \vec{r} \cdot \frac{d\vec{r}}{dt}$$

$$2 \vec{r} \cdot \frac{d\vec{r}}{dt} = 0$$

$$\vec{r} \cdot \frac{d\vec{r}}{dt} = 0$$

Again differentiate w.r. t t

$$\frac{d}{dt} \left(\vec{r} \cdot \frac{d\vec{r}}{dt} \right) = \frac{d}{dt} (0)$$

$$\vec{r} \cdot \frac{d^2\vec{r}}{dt^2} + \frac{d\vec{r}}{dt} \cdot \frac{d\vec{r}}{dt} = 0 \quad \therefore \frac{d\vec{r}}{dt} \cdot \frac{d\vec{r}}{dt} = \left(\frac{d\vec{r}}{dt} \right)^2$$

$$\vec{r} \cdot \frac{d^2\vec{r}}{dt^2} + \left(\frac{d\vec{r}}{dt} \right)^2 = 0 \text{-----(ii)}$$

Adding (i) & (ii)

$$\vec{r} \cdot \vec{r} + \vec{r} \cdot \frac{d^2\vec{r}}{dt^2} + \left(\frac{d\vec{r}}{dt} \right)^2 = 4 + 0$$

$$\vec{r} \cdot \left(\vec{r} \times \frac{d^2\vec{r}}{dt^2} \right) + \left(\frac{d\vec{r}}{dt} \right)^2 = 4$$

Hence proved.

Q#21: If \vec{f}, \vec{g} & \vec{h} are vector function of scalar variable t . then show that

(i)
$$\frac{d}{dt} [\vec{f} \cdot (\vec{g} \times \vec{h})] = \vec{f}' \cdot (\vec{g} \times \vec{h}) + \vec{f} \cdot (\vec{g}' \times \vec{h}) + \vec{f} \cdot (\vec{g} \times \vec{h}')$$

(ii)
$$\frac{d}{dt} [\vec{f} \times (\vec{g} \times \vec{h})] = \vec{f}' \times (\vec{g} \times \vec{h}) + \vec{f} \times (\vec{g}' \times \vec{h}) + \vec{f} \times (\vec{g} \times \vec{h}')$$

(i)
$$\frac{d}{dt} [\vec{f} \cdot (\vec{g} \times \vec{h})] = \vec{f}' \cdot (\vec{g} \times \vec{h}) + \vec{f} \cdot (\vec{g}' \times \vec{h}) + \vec{f} \cdot (\vec{g} \times \vec{h}')$$

Solution: Let

$$\frac{d}{dt} [\vec{f} \cdot (\vec{g} \times \vec{h})] = \frac{d}{dt} \vec{f} \cdot (\vec{g} \times \vec{h}) + \vec{f} \cdot (\frac{d}{dt} \vec{g} \times \vec{h}) + \vec{f} \cdot (\vec{g} \times \frac{d}{dt} \vec{h})$$

$$\frac{d}{dt} [\vec{f} \cdot (\vec{g} \times \vec{h})] = \vec{f}' \cdot (\vec{g} \times \vec{h}) + \vec{f} \cdot (\vec{g}' \times \vec{h}) + \vec{f} \cdot (\vec{g} \times \vec{h}') \text{ Hence proved.}$$

(ii)
$$\frac{d}{dt} [\vec{f} \times (\vec{g} \times \vec{h})] = \vec{f}' \times (\vec{g} \times \vec{h}) + \vec{f} \times (\vec{g}' \times \vec{h}) + \vec{f} \times (\vec{g} \times \vec{h}')$$

Solution: Let

$$\frac{d}{dt} [\vec{f} \times (\vec{g} \times \vec{h})] = \frac{d}{dt} \vec{f} \times (\vec{g} \times \vec{h}) + \vec{f} \times (\frac{d}{dt} \vec{g} \times \vec{h}) + \vec{f} \times (\vec{g} \times \frac{d}{dt} \vec{h})$$

$$\frac{d}{dt} [\vec{f} \times (\vec{g} \times \vec{h})] = \vec{f}' \times (\vec{g} \times \vec{h}) + \vec{f} \times (\vec{g}' \times \vec{h}) + \vec{f} \times (\vec{g} \times \vec{h}') \text{ Hence proved.}$$

Q#22: If \vec{f}, \vec{g} & \vec{h} are vector functions of scalar variable t and if

$\vec{f}' = \vec{h} \times \vec{f}$ & $\vec{g}' = \vec{h} \times \vec{g}$ Then show that $\frac{d}{dt} (\vec{f} \times \vec{g}) = \vec{h} \times (\vec{f} \times \vec{g})$.

Solution: Taking L.H.S

$$\frac{d}{dt} (\vec{f} \times \vec{g}) = \frac{d\vec{f}}{dt} \times \vec{g} + \vec{f} \times \frac{d\vec{g}}{dt} = \vec{f}' \times \vec{g} + \vec{f} \times \vec{g}'$$

Using given values

$$\vec{f}' = \vec{h} \times \vec{f} \quad \& \quad \vec{g}' = \vec{h} \times \vec{g}$$

$$\begin{aligned} \frac{d}{dt} (\vec{f} \times \vec{g}) &= (\vec{h} \times \vec{f}) \times \vec{g} + \vec{f} \times (\vec{h} \times \vec{g}) \\ &= (\vec{h} \cdot \vec{g}) \vec{f} - (\vec{f} \cdot \vec{g}) \vec{h} + (\vec{f} \cdot \vec{g}) \vec{h} - (\vec{f} \cdot \vec{h}) \vec{g} \end{aligned}$$

$$\frac{d}{dt} (\vec{f} \times \vec{g}) = (\vec{h} \cdot \vec{g}) \vec{f} - (\vec{f} \cdot \vec{h}) \vec{g} \text{ -----(i)}$$

Now taking R.H.S

$$\vec{h} \times (\vec{g} \times \vec{f}) = (\vec{h} \cdot \vec{g}) \vec{f} - (\vec{f} \cdot \vec{h}) \vec{g} \text{ -----(ii)}$$

From (i) & (ii) Hence proved that

$$\frac{d}{dt} (\vec{f} \times \vec{g}) = \vec{h} \times (\vec{f} \times \vec{g})$$

Q#23: If $\hat{u}(t)$ is a unit vector then show that $\hat{u} \cdot \left(\hat{u} \times \frac{d^2 \hat{u}}{dt^2} \right) + \left(\frac{d\hat{u}}{dt} \right)^2 = 1$.

Solution: If $\hat{u}(t)$ is a unit vector. Then

$$\hat{u} \cdot \hat{u} = |\hat{u}|^2$$

$$\hat{u} \cdot \hat{u} = 1 \quad \text{-----}(i) \qquad \qquad \qquad \therefore |\hat{u}| = 1$$

Differentiate (i) w. r. t t $\frac{d}{dt} (\hat{u} \cdot \hat{u}) = \frac{d}{dt} (1)$

$$\frac{d\hat{u}}{dt} \cdot \hat{u} + \hat{u} \cdot \frac{d\hat{u}}{dt} = 0 \qquad \qquad \qquad \therefore \frac{d\hat{u}}{dt} \cdot \hat{u} = -\hat{u} \cdot \frac{d\hat{u}}{dt}$$

$$2 \hat{u} \cdot \frac{d\hat{u}}{dt} = 0$$

$$\hat{u} \cdot \frac{d\hat{u}}{dt} = 0$$

Again differentiate w.r. t t $\frac{d}{dt} \left(\hat{u} \cdot \frac{d\hat{u}}{dt} \right) = \frac{d}{dt} (0)$

$$\hat{u} \cdot \frac{d^2 \hat{u}}{dt^2} + \frac{d\hat{u}}{dt} \cdot \frac{d\hat{u}}{dt} = 0 \qquad \qquad \qquad \therefore \frac{d\hat{u}}{dt} \cdot \frac{d\hat{u}}{dt} = - \left(\frac{d\hat{u}}{dt} \right)^2$$

$$\hat{u} \cdot \frac{d^2 \hat{u}}{dt^2} + \left(\frac{d\hat{u}}{dt} \right)^2 = 0 \quad \text{-----}(ii)$$

Adding (i) & (ii)

$$\hat{u} \cdot \hat{u} + \hat{u} \cdot \frac{d^2 \hat{u}}{dt^2} + \left(\frac{d\hat{u}}{dt} \right)^2 = 1 + 0$$

$$\hat{u} \cdot \left(\hat{u} \cdot \frac{d^2 \hat{u}}{dt^2} \right) + \left(\frac{d\hat{u}}{dt} \right)^2 = 1$$

Hence proved.

Q#24(i) Show that $\frac{d}{dt} [\vec{f} \times \vec{g}' - \vec{f}' \times \vec{g}] = \vec{f} \times \vec{g}'' - \vec{f}'' \times \vec{g}$

Solution: Let

$$\begin{aligned} \frac{d}{dt} [\vec{f} \times \vec{g}' - \vec{f}' \times \vec{g}] &= \frac{d}{dt} [\vec{f} \times \vec{g}'] - \frac{d}{dt} [\vec{f}' \times \vec{g}] \\ &= \left[\frac{d\vec{f}}{dt} \times \vec{g}' + \vec{f} \times \frac{d}{dt}(\vec{g}') \right] - \left[\frac{d}{dt}(\vec{f}') \times \vec{g} + \vec{f}' \times \frac{d\vec{g}}{dt} \right] \\ &= \vec{f}' \times \vec{g}' + \vec{f} \times \vec{g}'' - \vec{f}'' \times \vec{g} - \vec{f}' \times \vec{g}' \end{aligned}$$

$$\frac{d}{dt} [\vec{f} \times \vec{g}' - \vec{f}' \times \vec{g}] = \vec{f} \times \vec{g}'' - \vec{f}'' \times \vec{g}$$

Hence proved

Q#24 (ii) If $\hat{f}(t)$ is a unit vector in the direction of vector $\vec{g}(t)$. Then show that $\hat{f} \times \hat{f}' = \frac{\vec{g} \times \vec{g}'}{g \cdot \vec{g}}$.

Solution: If $\hat{f}(t)$ is a unit vector in the direction of vector $\vec{g}(t)$. Then

$$\hat{f} = \frac{\vec{g}}{g} \qquad \therefore |\vec{g}| = g$$

$$g \hat{f} = \vec{g}$$

$$\vec{g} = g \hat{f} \text{-----(i)}$$

Differentiate w. r. t t

$$\vec{g}' = g \hat{f}' + g' \hat{f} \text{-----(ii)}$$

Taking cross product of equation (i) & (ii)

$$\vec{g} \times \vec{g}' = g \hat{f} \times [g \hat{f}' + g' \hat{f}]$$

$$\vec{g} \times \vec{g}' = g^2 (\hat{f} \times \hat{f}') + g g' (\hat{f} \times \hat{f})$$

$$\vec{g} \times \vec{g}' = (\vec{g} \cdot \vec{g}') (\hat{f} \times \hat{f}') + g g' (0) \qquad \therefore g^2 = \vec{g} \cdot \vec{g} \text{ \& } \hat{f} \times \hat{f} = 0$$

$$\vec{g} \times \vec{g}' = (\vec{g} \cdot \vec{g}') (\hat{f} \times \hat{f}') + 0$$

$$\vec{g} \times \vec{g}' = (\vec{g} \cdot \vec{g}') (\hat{f} \times \hat{f}')$$

$$\frac{\vec{g} \times \vec{g}'}{\vec{g} \cdot \vec{g}'} = \hat{f} \times \hat{f}'$$

Hence proved

$$\hat{f} \times \hat{f}' = \frac{\vec{g} \times \vec{g}'}{\vec{g} \cdot \vec{g}'}$$

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Q#25: If $\vec{r}(t) = 2t\hat{i} + t^2\hat{j} + \frac{1}{3}t^3\hat{k}$ **then show that**

(i) $\frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} = 2t^2\hat{i} - 4t\hat{j} + 4\hat{k}$ (ii) $\left[\frac{d\vec{r}}{dt} \quad \frac{d^2\vec{r}}{dt^2} \quad \frac{d^3\vec{r}}{dt^3}\right] = 8$ (iii) $\vec{r} \cdot \frac{d\vec{r}}{dt} = r \frac{dr}{dt}$ **here** $|\vec{r}| = r$.

Solution: Given vector function $\vec{r} = 2t\hat{i} + t^2\hat{j} + \frac{1}{3}t^3\hat{k}$

Then $\frac{d\vec{r}}{dt} = 2\hat{i} + 2t\hat{j} + \frac{1}{3}3t^2\hat{k} = 2\hat{i} + 2t\hat{j} + t^2\hat{k}$

$$\frac{d^2\vec{r}}{dt^2} = 0\hat{i} + 2\hat{j} + 2t\hat{k} \quad \& \quad \frac{d^3\vec{r}}{dt^3} = 0\hat{i} + 0\hat{j} + 2\hat{k}$$

(i) $\frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2 & 2t & t^2 \\ 0 & 2 & 2t \end{vmatrix} = \hat{i} \begin{vmatrix} 2t & t^2 \\ 2 & 2t \end{vmatrix} - \hat{j} \begin{vmatrix} 2 & t^2 \\ 0 & 2t \end{vmatrix} + \hat{k} \begin{vmatrix} 2 & 2t \\ 0 & 2 \end{vmatrix}$

$$= \hat{i} [(2t)(2t) - (2)(t^2)] - \hat{j} [(2)(2t) - (0)(t^2)] + \hat{k} [(2)(2) - (0)(2t)]$$

$$= \hat{i} [4t^2 - 2t^2] - \hat{j} [4t - 0] + \hat{k} [4 - 0] = 2t^2\hat{i} - 4t\hat{j} + 4\hat{k}$$

(ii) $\left[\frac{d\vec{r}}{dt} \quad \frac{d^2\vec{r}}{dt^2} \quad \frac{d^3\vec{r}}{dt^3}\right] = \frac{d\vec{r}}{dt} \cdot \left(\frac{d^2\vec{r}}{dt^2} \times \frac{d^3\vec{r}}{dt^3}\right) = \begin{vmatrix} 2 & 2t & t^2 \\ 0 & 2 & 2t \\ 0 & 0 & 2 \end{vmatrix} \quad \therefore \text{Expanding by R3}$

$$= 0 + 0 + 2 \begin{vmatrix} 2 & 2t \\ 0 & 2 \end{vmatrix} = 2 [(2)(2) - (0)(2t)] = 2(4 - 0) = 2(4)$$

$\left[\frac{d\vec{r}}{dt} \quad \frac{d^2\vec{r}}{dt^2} \quad \frac{d^3\vec{r}}{dt^3}\right] = 8$ **Hence proved.**

(iii) **Given** $\vec{r} = 2t\hat{i} + t^2\hat{j} + \frac{1}{3}t^3\hat{k}$

Now $\vec{r} \cdot \frac{d\vec{r}}{dt} = (2t\hat{i} + t^2\hat{j} + \frac{1}{3}t^3\hat{k}) \cdot (2\hat{i} + 2t\hat{j} + t^2\hat{k}) = 2t(2) + t^2(2t) + (\frac{1}{3}t^3)(t^2)$

$$\vec{r} \cdot \frac{d\vec{r}}{dt} = 4t + 2t^3 + \frac{1}{3}t^5 \text{-----(i)}$$

Then $|\vec{r}| = \sqrt{(2t)^2 + (t^2)^2 + (\frac{1}{3}t^3)^2} = \sqrt{4t^2 + t^4 + \frac{1}{9}t^6}$

Taking square on both sides

$$r^2 = 4t^2 + t^4 + \frac{1}{9}t^6$$

Differentiate w.r.t t $2r \frac{dr}{dt} = 8t + 4t^3 + \frac{1}{9}(6t^5) = 8t + 4t^3 + \frac{2}{3}t^5$

Dividing by $r \frac{dr}{dt} = 4t + 2t^3 + \frac{1}{3}t^5 \text{-----(ii)}$

From (i) & (ii) hence proved $\vec{r} \cdot \frac{d\vec{r}}{dt} = r \frac{dr}{dt}$

Q#26: If $\vec{f}(t)$ is a vector function then show that $\frac{d}{dt} \left(\frac{\vec{f}}{|\vec{f}|} \right) = \frac{\vec{f}'(\vec{f} \cdot \vec{f}) - \vec{f}(\vec{f} \cdot \vec{f}')}{(\vec{f} \cdot \vec{f})^{3/2}}$.

Solution: Let $\vec{f} = f_1 \hat{i} + f_2 \hat{j} + f_3 \hat{k}$

Taking product with itself

$$\vec{f} \cdot \vec{f} = (f_1 \hat{i} + f_2 \hat{j} + f_3 \hat{k}) \cdot (f_1 \hat{i} + f_2 \hat{j} + f_3 \hat{k}) = f_1^2 + f_2^2 + f_3^2 \text{ -----(i)}$$

Taking magnitude of given vector.

$$|\vec{f}| = \sqrt{f_1^2 + f_2^2 + f_3^2}$$

$$|\vec{f}| = (\vec{f} \cdot \vec{f})^{1/2} \text{ -----(ii) using equ.(i)}$$

If $\vec{f}' = f_1' \hat{i} + f_2' \hat{j} + f_3' \hat{k}$

Then $\vec{f} \cdot \vec{f}' = |\vec{f}| |\vec{f}'| \text{ -----(iii)}$

Now taking

$$\begin{aligned} \text{L.H.S} &= \frac{d}{dt} \left(\frac{\vec{f}}{|\vec{f}|} \right) = \frac{|\vec{f}| \vec{f}' - \vec{f} |\vec{f}'|}{(|\vec{f}|)^2} && \therefore \text{By applying quotient rule} \\ &= \frac{|\vec{f}| [|\vec{f}| \vec{f}' - \vec{f} |\vec{f}'|]}{(|\vec{f}|)^3} && \therefore \text{Multiplying and dividing by } |\vec{f}| \\ &= \frac{|\vec{f}| |\vec{f}| \vec{f}' - \vec{f} |\vec{f}'| |\vec{f}|}{[(\vec{f} \cdot \vec{f})^{1/2}]^3} && \therefore \text{From(ii) } |\vec{f}| = (\vec{f} \cdot \vec{f})^{1/2} \\ &= \frac{(|\vec{f}|)^2 \vec{f}' - \vec{f} (\vec{f} \cdot \vec{f}')}{(\vec{f} \cdot \vec{f})^{3/2}} && \therefore \text{From(iii) } \vec{f} \cdot \vec{f}' = |\vec{f}| |\vec{f}'| \\ &= \frac{(\vec{f} \cdot \vec{f}) \vec{f}' - \vec{f} (\vec{f} \cdot \vec{f}')}{(\vec{f} \cdot \vec{f})^{3/2}} && \therefore \vec{f} \cdot \vec{f} = (|\vec{f}|)^2 \\ &= \text{R.H.S} \end{aligned}$$

Hence proved That L.H.S =R.H.S

Q#27: Show that

(i) Necessary and sufficient condition for a vector \vec{f} of scalar variable t to be a constant is $\frac{d\vec{f}}{dt} = 0$

Proof: By given condition. That \vec{f} be constant vector. Then $\vec{f} = \text{constant}$

Differentiate w.r.t t $\frac{d\vec{f}}{dt} = \frac{d}{dt}(\text{constant}) \Rightarrow \frac{d\vec{f}}{dt} = 0$

Conversely, suppose that $\frac{d\vec{f}}{dt} = 0 \Rightarrow d\vec{f} = 0 dt$

On integrating both sides $\int d\vec{f} = \int 0 dt$

$$\vec{f} = 0 \cdot t + \text{constant} \Rightarrow \vec{f} = \text{constant}$$

Hence prove that

The Necessary and sufficient condition for a vector \vec{f} of scalar variable t to be a constant is $\frac{d\vec{f}}{dt} = 0$.

(ii) Necessary and sufficient condition for a vector \vec{f} of scalar variable t to have a constant magnitude is $\vec{f} \cdot \frac{d\vec{f}}{dt} = 0$.

Proof: By given condition. That vector \vec{f} have a constant magnitude. Then $|\vec{f}| = \text{constant}$

Taking square on both sides $|\vec{f}|^2 = (\text{constant})^2 = \text{constant}$

We know that $\vec{f} \cdot \vec{f} = |\vec{f}|^2$ then $\vec{f} \cdot \vec{f} = \text{constant}$

Differentiate w.r.t t $\frac{d}{dt}(\vec{f} \cdot \vec{f}) = \frac{d}{dt}(\text{constant})$

$$\frac{d\vec{f}}{dt} \cdot \vec{f} + \vec{f} \cdot \frac{d\vec{f}}{dt} = 0 \qquad \therefore \vec{f} \cdot \frac{d\vec{f}}{dt} = \frac{d\vec{f}}{dt} \cdot \vec{f}$$

$$2 \vec{f} \cdot \frac{d\vec{f}}{dt} = 0 \Rightarrow \vec{f} \cdot \frac{d\vec{f}}{dt} = 0$$

Conversely, suppose that $\vec{f} \cdot \frac{d\vec{f}}{dt} = 0 \qquad \therefore \vec{f} \cdot \frac{d\vec{f}}{dt} = f \frac{df}{dt}$

$$f \frac{df}{dt} = 0 \Rightarrow f df = 0 dt$$

on integrating both sides $\int f df = \int 0 dt$

$$\Rightarrow \frac{|\vec{f}|^2}{2} = 0 \cdot t + \text{constant} \Rightarrow |\vec{f}|^2 = 2(\text{constant})$$

Taking square-root on both sides $|\vec{f}| = \sqrt{2(\text{constant})} \Rightarrow |\vec{f}| = \text{constant}$

Hence prove that Necessary and sufficient condition for a vector \vec{f} of scalar variable t to have a constant magnitude is $\vec{f} \cdot \frac{d\vec{f}}{dt} = 0$

(iii) Necessary and sufficient condition for a vector \vec{f} of scalar variable t to have a constant direction is $\vec{f} \times \frac{d\vec{f}}{dt} = 0$

Proof: Let \hat{r} be unit vector in the direction of vector \vec{f} . By given condition, that direction is constant .

$\hat{r} = \text{constant}$ Then $\frac{d\hat{r}}{dt} = 0$ -----(i)

As we know that $\hat{r} = \frac{\vec{f}}{f} \implies \vec{f} = f\hat{r}$ -----(ii) $\therefore |\vec{f}| = f$

Differentiate w.r.t t $\frac{d\vec{f}}{dt} = \frac{d}{dt} (f\hat{r})$

$\frac{d\vec{f}}{dt} = \frac{df}{dt} \hat{r} + f \frac{d\hat{r}}{dt}$ -----(iii)

Takin cross product of equation (ii) & (iii)

$\vec{f} \times \frac{d\vec{f}}{dt} = f\hat{r} \times \left(\frac{df}{dt} \hat{r} + f \frac{d\hat{r}}{dt} \right)$

$\vec{f} \times \frac{d\vec{f}}{dt} = f \frac{df}{dt} (\hat{r} \times \hat{r}) + f^2 \left(\hat{r} \times \frac{d\hat{r}}{dt} \right)$

$\vec{f} \times \frac{d\vec{f}}{dt} = f \frac{df}{dt} (0) + f^2 \left(\hat{r} \times \frac{d\hat{r}}{dt} \right) \quad \therefore \hat{r} \times \hat{r} = 0$

$\vec{f} \times \frac{d\vec{f}}{dt} = 0 + f^2 \left(\hat{r} \times \frac{d\hat{r}}{dt} \right)$

$\vec{f} \times \frac{d\vec{f}}{dt} = f^2 \left(\hat{r} \times \frac{d\hat{r}}{dt} \right)$ -----(iv)

$\vec{f} \times \frac{d\vec{f}}{dt} = f^2 (\hat{r} \times 0) \quad \therefore \text{From (i)} \quad \frac{d\hat{r}}{dt} = 0$

$\vec{f} \times \frac{d\vec{f}}{dt} = 0$

Conversely, suppose that

$\vec{f} \times \frac{d\vec{f}}{dt} = 0$

Then equation (iv) will become

$f^2 \left(\hat{r} \times \frac{d\hat{r}}{dt} \right) = 0 \implies \hat{r} \times \frac{d\hat{r}}{dt} = 0$

Here $\hat{r} \neq 0$ but $\frac{d\hat{r}}{dt} = 0$ Therefore $\hat{r} = \text{constant}$

Hence prove that Necessary and sufficient condition for a vector \vec{f} of scalar variable t to have a constant direction is $\vec{f} \times \frac{d\vec{f}}{dt} = 0$.

Q#28: A particle that move along a curve . $x = 2t^2, y = t^2 - 4t, z = 3t - 5$. Where t is time Find component of velocity and acceleration at $t=1$ in the direction of $\hat{i} + 3\hat{j} + 3\hat{k}$.

Solution: Let $\vec{r}(t)$ be a position vector. Then $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$

Putting $x = 2t^2, y = t^2 - 4t, z = 3t - 5$

$$\vec{r} = 2t^2\hat{i} + (t^2 - 4t)\hat{j} + (3t - 5)\hat{k}$$

Velocity: Differentiate w. r. t t . $\vec{v} = \frac{d\vec{r}}{dt} = 4t\hat{i} + (2t - 4)\hat{j} + 3\hat{k}$

At $t = 1$: $\vec{v} = 4\hat{i} + [2(2) - 4]\hat{j} + 3\hat{k} = 4\hat{i} - 2\hat{j} + 3\hat{k} \Rightarrow \vec{v} = 4\hat{i} - 2\hat{j} + 3\hat{k}$

Acceleration: Differentiate w. r. t t . $\vec{a} = \frac{d\vec{v}}{dt} = 0\hat{i} + 2\hat{j} + 0\hat{k}$

At $t = 1$: $\vec{a} = 4\hat{i} + 2\hat{j} + 0\hat{k} \Rightarrow \vec{a} = 4\hat{i} + 2\hat{j}$

Let $\vec{u} = \hat{i} + 3\hat{j} + 3\hat{k}$ **Then** $\hat{u} = \frac{\vec{u}}{|\vec{u}|} = \frac{\hat{i} + 3\hat{j} + 3\hat{k}}{\sqrt{(1)^2 + (3)^2 + (3)^2}} = \frac{\hat{i} + 3\hat{j} + 3\hat{k}}{\sqrt{1+9+9}} = \frac{\hat{i} + 3\hat{j} + 3\hat{k}}{\sqrt{19}}$

Now

Component of \vec{v} along $\vec{u} = \vec{v} \cdot \hat{u} = (4\hat{i} - 2\hat{j} + 3\hat{k}) \cdot \left(\frac{\hat{i} + 3\hat{j} + 3\hat{k}}{\sqrt{19}}\right) = \frac{(4\hat{i} - 2\hat{j} + 3\hat{k}) \cdot (\hat{i} + 3\hat{j} + 3\hat{k})}{\sqrt{19}} = \frac{4 - 6 + 9}{\sqrt{19}} = \frac{7}{\sqrt{19}}$

Component of \vec{a} along $\vec{u} = \vec{a} \cdot \hat{u} = (4\hat{i} + 2\hat{j} + 0\hat{k}) \cdot \left(\frac{\hat{i} + 3\hat{j} + 3\hat{k}}{\sqrt{19}}\right) = \frac{(4\hat{i} + 2\hat{j} + 0\hat{k}) \cdot (\hat{i} + 3\hat{j} + 3\hat{k})}{\sqrt{19}} = \frac{4 + 6 + 0}{\sqrt{19}} = \frac{10}{\sqrt{19}}$

Q#29: A particle moves , so that its position vector is given by $\vec{r} = \cos \omega t \hat{i} + \sin \omega t \hat{j}$. Where ω is constant. Show that (i) the velocity \vec{v} of a particle is perpendicular to \vec{r} (ii) The acceleration \vec{a} is directed toward the origin and has magnitude proportional to the displacement \vec{r} from the origin. (iii) $\vec{r} \times \vec{v} = \vec{c}$. (\vec{c} is constant vector)

Solution: Given position vector $\vec{r} = \cos \omega t \hat{i} + \sin \omega t \hat{j}$ -----(i)

Velocity: Differentiate w. r. t t . $\vec{v} = \frac{d\vec{r}}{dt} = -\omega \sin \omega t \hat{i} + \omega \cos \omega t \hat{j}$ -----(ii)

Acceleration: Differentiate w. r. t t . $\vec{a} = \frac{d\vec{v}}{dt} = -\omega^2 \cos \omega t \hat{i} - \omega^2 \sin \omega t \hat{j}$ -----(iii)

(i) we have to prove $\vec{v} \perp \vec{r}$ for this $\vec{v} \cdot \vec{r} = 0$

$$\vec{v} \cdot \vec{r} = (-\omega \sin \omega t \hat{i} + \omega \cos \omega t \hat{j}) \cdot (\cos \omega t \hat{i} + \sin \omega t \hat{j}) = -\omega \sin \omega t \cos \omega t + \omega \sin \omega t \cos \omega t$$

$$\vec{v} \cdot \vec{r} = 0$$

Hence prove $\vec{v} \perp \vec{r}$

(ii) We have to prove $\vec{a} \propto -\vec{r}$.

For this using (iii) $\vec{a} = -\omega^2 \cos \omega t \hat{i} - \omega^2 \sin \omega t \hat{j} = -\omega^2 [\cos \omega t \hat{i} + \sin \omega t \hat{j}]$

$$\vec{a} = -\omega^2 \vec{r} \quad \therefore \text{From (i)}$$

This shows that $\vec{a} \propto -\vec{r}$. Negative sign indicate the acceleration \vec{a} is directed toward the origin .

(iii) We have to prove $\vec{r} \times \vec{v} = \vec{c}$. (\vec{c} is constant vector)

$$\vec{r} \times \vec{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \cos \omega t & \sin \omega t & 0 \\ -\omega \sin \omega t & \omega \cos \omega t & 0 \end{vmatrix} = \hat{k} \begin{vmatrix} \cos \omega t & \sin \omega t \\ -\omega \sin \omega t & \omega \cos \omega t \end{vmatrix} \quad \therefore \text{Expanding by } C_3$$

$$= \hat{k}[(\cos \omega t)(\omega \cos \omega t) - (-\omega \sin \omega t)(\sin \omega t)] = \hat{k}[\omega^2 \cos^2 \omega t + \omega^2 \sin^2 \omega t]$$

$$= \hat{k}[\omega^2 (\cos^2 \omega t + \sin^2 \omega t)]$$

$$\vec{r} \times \vec{v} = \omega^2 \hat{k} \quad \text{Hence proved} \quad \vec{r} \times \vec{v} = \vec{c} \quad \text{Here } \vec{c} = \omega^2 \hat{k} (\vec{c} \text{ is constant vector})$$

Q#30: A particle moves along a curve whose parametric equation are $x = e^{-t}$, $y = 2 \cos 3t$, $z = 2 \sin 3t$,

where t is time

(a) Determine its velocity and acceleration at any time t (b) Find magnitudes of velocity and acceleration at $t = 0$.

Solution: Let $\vec{r}(t)$ be a position vector. Then $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$

Putting $x = e^{-t}$, $y = 2 \cos 3t$ and $z = 2 \sin 3t$

$$\vec{r} = e^{-t}\hat{i} + 2 \cos 3t\hat{j} + 2 \sin 3t\hat{k}$$

(a) **Velocity:** Differentiate w. r. t t . $\vec{v} = \frac{d\vec{r}}{dt} = -e^{-t}\hat{i} - 6 \sin 3t\hat{j} + 6 \cos 3t\hat{k}$

Acceleration: Differentiate w. r. t t . $\vec{a} = \frac{d\vec{v}}{dt} = e^{-t}\hat{i} - 18 \cos 3t\hat{j} - 18 \sin 3t\hat{k}$

(b) **Magnitude of Velocity:** at $t = 0$

$$\vec{v} = -e^{-0}\hat{i} - 6 \sin 3(0)\hat{j} + 6 \cos 3(0)\hat{k} = -1\hat{i} - 0\hat{j} + 6\hat{k}$$

$$|\vec{v}| = \sqrt{(-1)^2 + (0)^2 + (6)^2} = \sqrt{1 + 0 + 36} = \sqrt{37}$$

Magnitude of Acceleration: at $t = 0$

$$\vec{a} = \frac{d\vec{v}}{dt} = e^{-0}\hat{i} - 18 \cos 3(0)\hat{j} - 18 \sin 3(0)\hat{k} = 1\hat{i} - 18\hat{j} + 0\hat{k}$$

$$|\vec{a}| = \sqrt{(1)^2 + (18)^2 + (0)^2} = \sqrt{1 + 324 + 0} = \sqrt{325}$$

Q#31: Find the velocity and acceleration of a particle moves along a curve whose parametric equation are

$x = 2 \sin 3t$, $y = 2 \cos 3t$ and $z = 8t$ at any time. Find the magnitude of velocity and acceleration.

Solution: Let $\vec{r}(t)$ be a position vector. Then $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$

Putting $x = 2 \sin 3t$, $y = 2 \cos 3t$ and $z = 8t$ **Then** $\vec{r} = 2 \sin 3t\hat{i} + 2 \cos 3t\hat{j} + 8t\hat{k}$

Velocity: Differentiate w. r. t t . $\vec{v} = \frac{d\vec{r}}{dt} = 6 \cos 3t\hat{i} - 6 \sin 3t\hat{j} + 8\hat{k}$

$$|\vec{v}| = \sqrt{(6 \cos 3t)^2 + (-6 \sin 3t)^2 + (8)^2} = \sqrt{36\cos^2 3t + 36\sin^2 3t + 64} = \sqrt{36[\cos^2 3t + \sin^2 3t] + 64} = \sqrt{100} = 10$$

Acceleration: Differentiate w. r. t t . $\vec{a} = \frac{d\vec{v}}{dt} = -18 \sin 3t\hat{i} - 18 \cos 3t\hat{j} + 0\hat{k}$

$$|\vec{a}| = \sqrt{(-18 \sin 3t)^2 + (-18 \cos 3t)^2 + (0)^2} = \sqrt{324\sin^2 3t + 324\cos^2 3t + 0} = \sqrt{324[\sin^2 3t + \cos^2 3t]} = \sqrt{324} = 18$$

Q#32: A particle that move along a curve . $x = 2t^2$, $y = t^2 - 4t$, $z = 3t - 5$. Where t is time Find component

of velocity and acceleration at $t=1$ in the direction of $\vec{b} = \hat{i} - 3\hat{j} + 2\hat{k}$.

Solution: Let $\vec{r}(t)$ be a position vector. Then $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$

Putting $x = 2t^2$, $y = t^2 - 4t$, $z = 3t - 5$ **Then** $\vec{r} = 2t^2\hat{i} + (t^2 - 4t)\hat{j} + (3t - 5)\hat{k}$

Velocity: Differentiate w. r. t t . $\vec{v} = \frac{d\vec{r}}{dt} = 4t\hat{i} + (2t - 4)\hat{j} + 3\hat{k}$

At $t = 1$: $\vec{v} = 4\hat{i} + [2(2) - 4]\hat{j} + 3\hat{k} = 4\hat{i} - 2\hat{j} + 3\hat{k} \Rightarrow \vec{v} = 4\hat{i} - 2\hat{j} + 3\hat{k}$

Acceleration: Differentiate w. r. t t $\vec{a} = \frac{d\vec{v}}{dt} = 0\hat{i} + 2\hat{j} + 0\hat{k}$

At $t = 1$ $\vec{a} = 4\hat{i} + 2\hat{j} + 0\hat{k} \Rightarrow \vec{a} = 4\hat{i} + 2\hat{j}$

Let $\vec{b} = \hat{i} - 3\hat{j} + 2\hat{k}$ **Then** $\hat{b} = \frac{\vec{b}}{|\vec{b}|} = \frac{\hat{i} - 3\hat{j} + 2\hat{k}}{\sqrt{(1)^2 + (-3)^2 + (2)^2}} = \frac{\hat{i} - 3\hat{j} + 2\hat{k}}{\sqrt{1+9+4}} = \frac{\hat{i} - 3\hat{j} + 2\hat{k}}{\sqrt{14}}$

Now

Component of \vec{v} along $\vec{b} = \vec{v} \cdot \hat{b} = (4\hat{i} - 2\hat{j} + 3\hat{k}) \cdot \left(\frac{\hat{i} - 3\hat{j} + 2\hat{k}}{\sqrt{14}}\right) = \frac{(4\hat{i} - 2\hat{j} + 3\hat{k}) \cdot (\hat{i} - 3\hat{j} + 2\hat{k})}{\sqrt{14}}$

$$= \frac{4+6+6}{\sqrt{14}} = \frac{16}{\sqrt{14}} = \frac{16\sqrt{14}}{\sqrt{14} \cdot \sqrt{14}} = \frac{16\sqrt{14}}{14} = \frac{8\sqrt{14}}{7}$$

Component of \vec{a} along $\vec{b} = \vec{a} \cdot \hat{b} = (4\hat{i} + 2\hat{j} + 0\hat{k}) \cdot \left(\frac{\hat{i} - 3\hat{j} + 2\hat{k}}{\sqrt{14}}\right) = \frac{(4\hat{i} + 2\hat{j} + 0\hat{k}) \cdot (\hat{i} - 3\hat{j} + 2\hat{k})}{\sqrt{14}}$

$$= \frac{4-6+0}{\sqrt{14}} = \frac{-2\sqrt{14}}{\sqrt{14} \cdot \sqrt{14}} = \frac{-2\sqrt{14}}{14} = \frac{-\sqrt{14}}{7}$$

INTEGRATION OF A VECTOR FUNCTION :

Integration of a vector function is define as the inverse or reverse process of differentiation.

Let $\vec{f}(t)$ & $\vec{g}(t)$ are two vector function . such that $\frac{d}{dt}[\vec{g}(t)] = \vec{f}(t)$ Then $\int \vec{f}(t) dt = \vec{g}(t) + c$

{ c is a constant of integration}. This is called indefinite integral of a vector function.

Definite integral is define on the interval [a, b] as $\int_a^b \vec{f}(t) dt = |\vec{g}(t)|_a^b = \vec{g}(b) - \vec{g}(a)$.

Theorem # I: *if $\vec{f}(t) = f_1(t)\hat{i} + f_2(t)\hat{j} + f_3(t)\hat{k}$ Then prove that*

$$\int \vec{f}(t) dt = \hat{i} \int f_1(t) dt + \hat{j} \int f_2(t) dt + \hat{k} \int f_3(t) dt$$

Proof: Let $\frac{d}{dt}[\vec{F}(t)] = \vec{f}(t)$ -----(i)

Then $\int \vec{f}(t) dt = \vec{F}(t)$ -----(ii)

Let $\vec{F}(t) = F_1(t)\hat{i} + F_2(t)\hat{j} + F_3(t)\hat{k}$ -----(iii)

Put in equation (i) $\frac{d}{dt} [F_1(t)\hat{i} + F_2(t)\hat{j} + F_3(t)\hat{k}] = \vec{f}(t)$

$$\frac{d}{dt} [F_1(t)] \hat{i} + \frac{d}{dt} [F_2(t)] \hat{j} + \frac{d}{dt} [F_3(t)] \hat{k} = f_1(t)\hat{i} + f_2(t)\hat{j} + f_3(t)\hat{k}$$

Equating coefficients of \hat{i}, \hat{j} & \hat{k}

$$\frac{d}{dt} [F_1(t)] = f_1(t) \Rightarrow \int f_1(t) dt = F_1(t)$$

$$\frac{d}{dt} [F_2(t)] = f_2(t) \Rightarrow \int f_2(t) dt = F_2(t)$$

$$\frac{d}{dt} [F_3(t)] = f_3(t) \Rightarrow \int f_3(t) dt = F_3(t)$$

Using values in equation (iii)

$$\vec{F}(t) = [\int f_1(t) dt]\hat{i} + [\int f_2(t) dt]\hat{j} + [\int f_3(t) dt]\hat{k}$$

Equation (ii) will become

$$\int \vec{f}(t) dt = \hat{i} \int f_1(t) dt + \hat{j} \int f_2(t) dt + \hat{k} \int f_3(t) dt$$

Hence proved.

Example#01: If $\vec{f}(t) = (t - t^2)\hat{i} + 2t^3\hat{j} - 3\hat{k}$ Find (i) $\int \vec{f}(t) dt$ (ii) $\int_1^2 \vec{f}(t) dt$

Solution: Given $\vec{f}(t) = (t - t^2)\hat{i} + 2t^3\hat{j} - 3\hat{k}$

(i) $\int \vec{f}(t) dt = \int [(t - t^2)\hat{i} + 2t^3\hat{j} - 3\hat{k}] dt = \hat{i}[\int (t - t^2) dt] + \hat{j}[2\int t^3 dt] + \hat{k}[-\int 3 dt]$

$$= \hat{i} \left[\frac{t^2}{2} - \frac{t^3}{3} \right] + \hat{j} \left[2 \left(\frac{t^4}{4} \right) \right] + \hat{k}[-3t]$$

$$\int \vec{f}(t) dt = \hat{i} \left[\frac{t^2}{2} - \frac{t^3}{3} \right] + \hat{j} \left[\frac{t^4}{2} \right] - 3\hat{k}[t] + c \quad \{c \text{ is constant of integration}\}$$

(ii) $\int_1^2 \vec{f}(t) dt = \hat{i} \left[\frac{t^2}{2} - \frac{t^3}{3} \right]_1^2 + \hat{j} \left[\frac{t^4}{2} \right]_1^2 - 3\hat{k}[t]_1^2 = \hat{i} \left[\left(\frac{2^2}{2} - \frac{2^3}{3} \right) - \left(\frac{1^2}{2} - \frac{1^3}{3} \right) \right] + \hat{j} \left[\frac{2^4}{2} - \frac{1^4}{2} \right] - 3\hat{k}[2 - 1]$

$$= \hat{i} \left[2 - \frac{8}{3} - \frac{1}{2} + \frac{1}{3} \right] + \hat{j} \left[8 - \frac{1}{2} \right] - 3\hat{k}[1]$$

$$\int_1^2 \vec{f}(t) dt = \frac{-5}{6}\hat{i} + \frac{15}{2}\hat{j} - 3\hat{k}$$

Example# 02: Solve $\vec{a} \times \frac{d^2\vec{v}}{dt^2} = \vec{b}$. \vec{a} & \vec{b} are constant vectors and \vec{v} is a vector function of t .

Solution: Given equation is $\vec{a} \times \frac{d^2\vec{v}}{dt^2} = \vec{b}$

On Integrating both sides $\int (\vec{a} \times \frac{d^2\vec{v}}{dt^2}) dt = \int \vec{b} dt$ -----(i)

Let $\frac{d}{dt} (\vec{a} \times \frac{d\vec{v}}{dt}) = \frac{d\vec{a}}{dt} \times \frac{d\vec{v}}{dt} + \vec{a} \times \frac{d^2\vec{v}}{dt^2} = \vec{a} \times \frac{d^2\vec{v}}{dt^2} \quad \therefore \frac{d\vec{a}}{dt} = 0$

$$d (\vec{a} \times \frac{d\vec{v}}{dt}) = (\vec{a} \times \frac{d^2\vec{v}}{dt^2}) dt$$

On Integrating both side $\int d (\vec{a} \times \frac{d\vec{v}}{dt}) = \int (\vec{a} \times \frac{d^2\vec{v}}{dt^2}) dt$

$$\vec{a} \times \frac{d\vec{v}}{dt} = \int \vec{b} dt \quad \therefore \text{From (i)}$$

$$\vec{a} \times \frac{d\vec{v}}{dt} = \vec{b}t + \vec{c} \text{ -----(ii)}$$

Let $\frac{d}{dt} (\vec{a} \times \vec{v}) = \frac{d\vec{a}}{dt} \times \frac{d\vec{v}}{dt} + \vec{a} \times \frac{d\vec{v}}{dt} = \vec{a} \times \frac{d\vec{v}}{dt} \quad \therefore \frac{d\vec{a}}{dt} = 0$

$$d (\vec{a} \times \vec{v}) = (\vec{a} \times \frac{d\vec{v}}{dt}) dt$$

On Integrating both sides $\int d (\vec{a} \times \vec{v}) = \int (\vec{a} \times \frac{d\vec{v}}{dt}) dt$

$$\vec{a} \times \vec{v} = \int (\vec{b}t + \vec{c}) dt$$

$$\vec{a} \times \vec{v} = \vec{b} \frac{t^2}{2} + \vec{c}t + \vec{d} \quad \{Where \vec{c} \& \vec{d} \text{ are constant of integration}\}$$

Example#03: Find the value of \vec{r} satisfying the equation $\frac{d^2\vec{r}}{dt^2} = \vec{a}$. Where \vec{a} is a constant of vector, also it is given that when $t=0$, $\vec{r} = 0$ and $\frac{d\vec{r}}{dt} = \vec{u}$.

Solution: Given equation $\frac{d^2\vec{r}}{dt^2} = \vec{a}$

On integrating both sides $\frac{d\vec{r}}{dt} = \vec{a} \int 1 dt = \vec{a} t + A$ -----(i)

When $t=0$ & $\frac{d\vec{r}}{dt} = \vec{u}$ then $\vec{u} = \vec{a} (0) + A \Rightarrow A = \vec{u}$

Using in equation (i) $\frac{d\vec{r}}{dt} = \vec{a} t + \vec{u}$

On integrating both sides $\vec{r} = \int (\vec{a} t + \vec{u}) dt = \vec{a} \frac{t^2}{2} + \vec{u} t + B$ -----(ii)

When $t=0$ & $\vec{r} = 0$ then $0 = \vec{a} \frac{(0)^2}{2} + \vec{u} (0) + B \Rightarrow B = 0$

Using in equation (ii) $\vec{r} = \vec{a} \frac{t^2}{2} + \vec{u} t$

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Exercise # 3.3

Q#01: Integrate the following w. r. t t.

(i) $(t^2 + 1)\hat{i} + (t^3 + t^2 + 3)\hat{j} + (2 - t)\hat{k}$ (ii) $\cos t \hat{i} + (t \sec^2 t + \tan t)\hat{j} + \sin t \hat{k}$

Solution: (i) Let $\vec{f}(t) = (t^2 + 1)\hat{i} + (t^3 + t^2 + 3)\hat{j} + (2 - t)\hat{k}$

On integrating both sides

$$\int \vec{f}(t) dt = \int [(t^2 + 1)\hat{i} + (t^3 + t^2 + 3)\hat{j} + (2 - t)\hat{k}] dt$$

$$= \hat{i} \int (t^2 + 1) dt + \hat{j} \int (t^3 + t^2 + 3) dt + \hat{k} \int (2 - t) dt$$

$$\int \vec{f}(t) dt = \hat{i} \left[\frac{t^3}{3} + t \right] + \hat{j} \left[\frac{t^4}{4} + \frac{t^3}{3} + 3t \right] + \hat{k} \left[2t - \frac{t^2}{2} \right]$$

(ii) Let $\vec{f}(t) = \cos t \hat{i} + (t \sec^2 t + \tan t)\hat{j} + \sin t \hat{k}$

On integrating both sides

$$\int \vec{f}(t) dt = \int [\cos t \hat{i} + (t \sec^2 t + \tan t)\hat{j} + \sin t \hat{k}] dt$$

$$= \hat{i} \int \cos t dt + \hat{j} \int (t \sec^2 t + \tan t) dt + \hat{k} \int \sin t dt$$

$$= \hat{i} [\sin t] + \hat{j} [t \tan t - \int \tan t dt + \int \tan t dt] + \hat{k} [-\cos t]$$

$$\int \vec{f}(t) dt = \sin t \hat{i} + t \tan t \hat{j} - \cos t \hat{k}$$

Q#02: If $\vec{r} = 5t^2\hat{i} + t\hat{j} - t^3\hat{k}$. Prove that $\int_1^3 \left(\vec{r} \times \frac{d^2\vec{r}}{dt^2} \right) dt = -52\hat{i} + 400\hat{j} - 40\hat{k}$

Solution: Given vector $\vec{r} = 5t^2\hat{i} + t\hat{j} - t^3\hat{k}$ Then $\frac{d\vec{r}}{dt} = 10t\hat{i} + \hat{j} - 3t^2\hat{k}$ & $\frac{d^2\vec{r}}{dt^2} = 10\hat{i} + 0\hat{j} - 6t\hat{k}$

Now $\vec{r} \times \frac{d^2\vec{r}}{dt^2} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 5t^2 & t & -t^3 \\ 10 & 0 & -6t \end{vmatrix} = \hat{i} \begin{vmatrix} t & -t^3 \\ 0 & -6t \end{vmatrix} - \hat{j} \begin{vmatrix} 5t^2 & -t^3 \\ 10 & -6t \end{vmatrix} + \hat{k} \begin{vmatrix} 5t^2 & t \\ 10 & 0 \end{vmatrix}$

$$= [-6t^2 - 0]\hat{i} - [-30t^3 + 10t^3]\hat{j} + [0 - 10t]\hat{k} = -6t^2\hat{i} - [-20t^3]\hat{j} + [-10t]\hat{k}$$

$$\vec{r} \times \frac{d^2\vec{r}}{dt^2} = -6t^2\hat{i} + 20t^3\hat{j} - 10t\hat{k}$$

On Integrating.

$$\int \left(\vec{r} \times \frac{d^2\vec{r}}{dt^2} \right) dt = \int [-6t^2\hat{i} + 20t^3\hat{j} - 10t\hat{k}] dt = \hat{i} [-6 \int t^2 dt] + \hat{j} [20 \int t^3 dt] + \hat{k} [-10 \int t dt]$$

$$\int \left(\vec{r} \times \frac{d^2\vec{r}}{dt^2} \right) dt = \hat{i} \left[-6 \left(\frac{t^3}{3} \right) \right] + \hat{j} \left[20 \left(\frac{t^4}{4} \right) \right] + \hat{k} \left[-10 \left(\frac{t^2}{2} \right) \right] = \hat{i} [-2t^3] + \hat{j} [5t^4] + \hat{k} [-5t^2]$$

Now applying limits

$$\int_1^3 \left(\vec{r} \times \frac{d^2\vec{r}}{dt^2} \right) dt = -2 \hat{i} [t^3]_1^3 + 5 \hat{j} [t^4]_1^3 - 5 \hat{k} [t^2]_1^3 = -2 \hat{i} [3^3 - 1^3] + 5 \hat{j} [3^4 - 1^4] - 5 \hat{k} [3^2 - 1^2]$$

$$= -2 \hat{i} [27 - 1] + 5 \hat{j} [81 - 1] - 5 \hat{k} [9 - 1] = -2 \hat{i} [26] + 5 \hat{j} [80] - 5 \hat{k} [8]$$

$$\int_1^3 \left(\vec{r} \times \frac{d^2\vec{r}}{dt^2} \right) dt = -52 \hat{i} + 400 \hat{j} - 40 \hat{k} \quad \text{Hence proved.}$$

Q#03: Determine a vector function which has $2 \cos 2t \hat{i} + 2 \sin 2t \hat{j} + 4 \hat{k}$ as its derivative

and $\hat{i} + \hat{j} + \hat{k}$ as its value at $t = 0$.

Solution: Let $\vec{f}(t)$ be a required vector which has derivative

$$\vec{f}'(t) = 2 \cos 2t \hat{i} + 2 \sin 2t \hat{j} + 4 \hat{k}$$

On integrating both sides

$$\vec{f}(t) = \int [2 \cos 2t \hat{i} + 2 \sin 2t \hat{j} + 4 \hat{k}] dt = \hat{i} [2 \int \cos 2t dt] + \hat{j} [2 \int \sin 2t dt] + \hat{k} [\int 4 dt]$$

$$= \hat{i} \left[2 \left(\frac{\sin 2t}{2} \right) \right] + \hat{j} \left[2 \left(\frac{-\cos 2t}{2} \right) \right] + \hat{k} [4t]$$

$$\vec{f}(t) = \sin 2t \hat{i} - \cos 2t \hat{j} + 4t \hat{k} + \vec{A} \quad \text{-----(i)}$$

Given initial values $t = 0$ & $\vec{f}(t) = \hat{i} + \hat{j} + \hat{k}$

$$\hat{i} + \hat{j} + \hat{k} = \sin 2(0) \hat{i} - \cos 2(0) \hat{j} + 4(0) \hat{k} + \vec{A}$$

$$\hat{i} + \hat{j} + \hat{k} = 0\hat{i} - 1\hat{j} + 0\hat{k} + \vec{A} \quad \Rightarrow \quad \vec{A} = \hat{i} + 2\hat{j} + \hat{k}$$

Using in equation (i)

$$\vec{f}(t) = \sin 2t \hat{i} - \cos 2t \hat{j} + 4t \hat{k} + \hat{i} + 2\hat{j} + \hat{k}$$

$$\vec{f}(t) = (1 + \sin 2t) \hat{i} + (2 - \cos 2t) \hat{j} + (4t + 1) \hat{k}$$

Q#04: Solve $\frac{d^2\vec{r}}{dt^2} = \vec{a}$ where \vec{a} is a constant of vector, given that $\vec{r} = 0$ and $\frac{d\vec{r}}{dt} = 0$ at $t=0$.

Solution: Given equation $\frac{d^2\vec{r}}{dt^2} = \vec{a}$

On integrating both sides $\frac{d\vec{r}}{dt} = \vec{a} \int 1 dt = \vec{a} t + A$ -----(i)

When $t=0$ & $\frac{d\vec{r}}{dt} = 0$ then $0 = \vec{a} (0) + A \Rightarrow A = 0$

Using in equation (i) $\frac{d\vec{r}}{dt} = \vec{a} t$

On integrating both sides $\vec{r} = \int (\vec{a} t) dt = \vec{a} \frac{t^2}{2} + B$ -----(ii)

When $t=0$ & $\vec{r} = 0$ then $0 = \vec{a} \frac{(0)^2}{2} + B \Rightarrow B = 0$

Using in equation (ii) $\vec{r} = \vec{a} \frac{t^2}{2}$

Q#05: If $\vec{f}''(t) = 4\hat{i}$ and $\vec{f}(t) = 0$ when $t = 0$ and $\vec{f}'(t) = 4\hat{j}$ when $t = 0$ show that the tip of position vector $\vec{f}(t)$ describes a parabola.

Solution: Given $\vec{f}''(t) = 4\hat{i}$

On integrating both sides $\vec{f}'(t) = \hat{i} \int 4 dt \Rightarrow \vec{f}'(t) = 4t\hat{i} + \vec{A}$ -----(i)

Given initial values at $t = 0$ & $\vec{f}'(t) = 4\hat{j} \Rightarrow 4\hat{j} = 4(0)\hat{i} + \vec{A} \Rightarrow \vec{A} = 4\hat{j}$

Using $\vec{A} = 4\hat{j}$ in Equation (i) $\vec{f}'(t) = 4t\hat{i} + 4\hat{j}$

On integrating both sides $\vec{f}(t) = \int [4t\hat{i} + 4\hat{j}] dt = \hat{i} [4 \int t dt] + \hat{j} \int 4 dt = \hat{i} [4(\frac{t^2}{2})] + \hat{j} [4t] + \vec{B}$
 $\vec{f}(t) = 2t^2\hat{i} + 4t\hat{j} + \vec{B}$ -----(ii)

Given initial values at $t = 0$ & $\vec{f}(t) = 0 \Rightarrow 0 = 2(0)^2\hat{i} + 4(0)\hat{j} + \vec{B}$
 $\Rightarrow \vec{B} = 0$

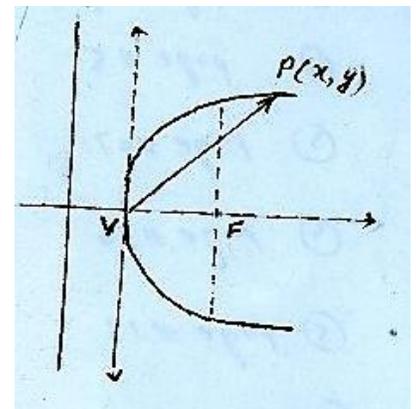
Using $\vec{B} = 0$ in Equation (ii) $\vec{f}(t) = 2t^2\hat{i} + 4t\hat{j}$ -----(iii)

Comparing equation (iii) with $\vec{f}(t) = x\hat{i} + y\hat{j}$

$x = 2t^2$ --- (a) & $y = 4t \Rightarrow t = \frac{y}{4}$

Using $t = \frac{y}{4}$ in equation (a) $x = 2(\frac{y}{4})^2 \Rightarrow x = 2 \cdot \frac{y^2}{16} \Rightarrow x = \frac{y^2}{8}$

$\Rightarrow y^2 = 8x$



This is an equation of parabola. Hence proved that the tip of position vector $\vec{f}(t)$ describes a parabola.

Q#06: Solve the equation $\frac{d^2\vec{v}}{dt^2} + 2\frac{d\vec{v}}{dt} + 4\vec{v} = 0$. Where \vec{v} is a vector function of t.

Solution: Given equation $\frac{d^2\vec{v}}{dt^2} + 2\frac{d\vec{v}}{dt} + 4\vec{v} = 0$

This is higher order differential equation we can solve it by the following method.

Put $\frac{d^2\vec{v}}{dt^2} = D^2\vec{v}$ & $\frac{d\vec{v}}{dt} = D\vec{v}$ in given equation

$$D^2\vec{v} + 2D\vec{v} + 4\vec{v} = 0 \Rightarrow [D^2 + 2D + 4]\vec{v} = 0$$

Characteristic equation:

$$D^2 + 2D + 4 = 0$$

{This is a quadratic equation in D}

By using quadratic formula $D = \frac{-2 \pm \sqrt{2^2 - 4(1)(4)}}{2(1)} = \frac{-2 \pm \sqrt{4 - 16}}{2} = \frac{-2 \pm \sqrt{-12}}{2} = \frac{-2 \pm 2\sqrt{3}i}{2} = -1 \pm \sqrt{3}i$

Characteristic Solution:

$$\vec{v}(t) = e^{-t} \{ \vec{a} \cos \sqrt{3} t + \vec{b} \sin \sqrt{3} t \}$$

Q#07 : Solve the equation $\frac{d^2\vec{v}}{dt^2} = \pm \omega^2 \vec{v}$ Where \vec{v} is a vector function of t & ω is a constant.

Solution: Given equation $\frac{d^2\vec{v}}{dt^2} = \pm \omega^2 \vec{v} \Rightarrow \frac{d^2\vec{v}}{dt^2} \mp \omega^2 \vec{v} = 0$

This is Higher order differential equation we can solve it by the following method.

Put $\frac{d^2\vec{v}}{dt^2} = D^2\vec{v}$

$$D^2\vec{v} \mp \omega^2 \vec{v} = 0 \Rightarrow [D^2 \mp \omega^2]\vec{v} = 0$$

Characteristic equation :

$$D^2 \mp \omega^2 = 0$$

$$D^2 = \pm \omega^2$$

$$D^2 = \omega^2$$

&

$$D^2 = -\omega^2$$

$$D = \pm \omega$$

&

$$D = \pm i \omega$$

∴ Taking square-root

Characteristic Solution:

$$\vec{v}(t) = \vec{a} e^{\omega t} + \vec{b} e^{-\omega t}$$

&

$$\vec{v}(t) = \vec{c} \cos \omega t + \vec{d} \sin \omega t$$

Q#08: If $\vec{v}(t)$ is a vector function, Solve the equation $\frac{d^2\vec{v}}{dt^2} = \vec{a}t + \vec{b}$ where \vec{a} and \vec{b} are constants and both $\vec{v}(t)$ & $\vec{v}'(t)$ both vanishes at $t=0$.

Solution: Given Equation is $\frac{d^2\vec{v}}{dt^2} = \vec{a}t + \vec{b}$ Or $\vec{v}''(t) = \vec{a}t + \vec{b}$

On integrating both sides $\vec{v}'(t) = \int(\vec{a}t + \vec{b}) dt$

$$\vec{v}'(t) = \vec{a} \frac{t^2}{2} + \vec{b}t + \vec{A} \text{-----(i)}$$

Given initial values at $t=0$ & $\vec{v}'(t)=0 \Rightarrow 0 = \vec{a} \frac{(0)^2}{2} + \vec{b}(0) + \vec{A} \Rightarrow \vec{A} = 0$

Using in Equation (i) $\vec{v}'(t) = \vec{a} \frac{t^2}{2} + \vec{b}t$

On integrating both sides $\vec{v}(t) = \int [\vec{a} \frac{t^2}{2} + \vec{b}t] dt = \hat{i} [\frac{1}{3} \int t^2 dt] + \hat{j} [\frac{1}{2} \int 4t dt] = \vec{a} \frac{t^3}{6} + \vec{b} \frac{t^2}{2} + \vec{B}$

$$\vec{v}(t) = \vec{a} \frac{t^3}{6} + \vec{b} \frac{t^2}{2} + \vec{B} \text{-----(ii)}$$

Given initial values at $t=0$ & $\vec{v}(t)=0 \Rightarrow 0 = \vec{a} \frac{(0)^3}{6} + \vec{b} \frac{(0)^2}{2} + \vec{B} \Rightarrow \vec{B} = 0$

$$\vec{v}(t) = \vec{a} \frac{t^3}{6} + \vec{b} \frac{t^2}{2}$$

Q#09: Solve the equation $\frac{d^3\vec{v}}{dt^3} - \frac{d^2\vec{v}}{dt^2} - 2 \frac{d\vec{v}}{dt} = 0$. Where \vec{v} is a vector function of t . Such that

$\vec{v} = 0$; $\frac{d\vec{v}}{dt} = 0$ & $\frac{d^2\vec{v}}{dt^2} = 0$ at $t = 0$.

Solution: Given equation

$$\frac{d^3\vec{v}}{dt^3} - \frac{d^2\vec{v}}{dt^2} - 2 \frac{d\vec{v}}{dt} = 0$$

This is higher order differential equation we can solve it by using the following method.

Put $\frac{d^3\vec{v}}{dt^3} = D^3\vec{v}$; $\frac{d^2\vec{v}}{dt^2} = D^2\vec{v}$ & $\frac{d\vec{v}}{dt} = D\vec{v}$ in given equation

$$D^3\vec{v} - D^2\vec{v} - 2D\vec{v} = 0$$

$$[D^3 - D^2 - 2D] \vec{v} = 0$$

Characteristic equation:

$$D^3 - D^2 - 2D = 0$$

$$D [D^2 - D - 2] = 0$$

Either $D=0$ or $D^2 - D - 2 = 0$ {This is a quadratic equation in D }

By using quadratic formula $D = \frac{-(-1) \pm \sqrt{(-1)^2 - 4(1)(-2)}}{2(1)} = \frac{1 \pm \sqrt{1+8}}{2} = \frac{1 \pm \sqrt{9}}{2} = \frac{1 \pm 3}{2}$

$D = \frac{1+3}{2} = \frac{4}{2} = 2$ or $D = \frac{1-3}{2} = \frac{-2}{2} = -1$ Hence $D = -1, 0, 2$

Characteristic Solution :

$\vec{v}(t) = c_1 e^{-t} + c_2 e^{0t} + c_3 e^{2t}$

$\vec{v}(t) = c_1 e^{-t} + c_2 + c_3 e^{2t}$ -----(A)

At $t=0$ & $\vec{v}(t) = \hat{i} \Rightarrow c_1 e^{-(0)} + c_2 + c_3 e^{2(0)} = \hat{i} \Rightarrow c_1 + c_2 + c_3 = \hat{i}$ -----(i)

$\vec{v}'(t) = -c_1 e^{-t} + 0 + 2c_3 e^{2t}$

At $t=0$ & $\vec{v}'(t) = \hat{j} \Rightarrow -c_1 e^{-(0)} + 2c_3 e^{2(0)} = \hat{j} \Rightarrow -c_1 + 2c_3 = \hat{j}$ -----(ii)

$\vec{v}''(t) = c_1 e^{-t} + 4c_3 e^{2t}$

At $t=0$ & $\vec{v}''(t) = \hat{k} \Rightarrow c_1 e^{-(0)} + 4c_3 e^{2(0)} = \hat{k} \Rightarrow c_1 + 4c_3 = \hat{k}$ -----(iii)

Adding (ii) & (iii) $6c_3 = \hat{j} + \hat{k} \Rightarrow c_3 = \frac{1}{6} [\hat{j} + \hat{k}]$

Using c_3 in equation (iii) $c_1 + 4 \left(\frac{1}{6} [\hat{j} + \hat{k}] \right) = \hat{k} \Rightarrow c_1 + \frac{2}{3} [\hat{j} + \hat{k}] = \hat{k}$

$\Rightarrow c_1 = \hat{k} - \frac{2}{3} [\hat{j} + \hat{k}] = \hat{k} - \frac{2}{3} \hat{j} - \frac{2}{3} \hat{k} \Rightarrow c_1 = -\frac{2}{3} \hat{j} + \frac{1}{3} \hat{k}$

Using values of c_1 & c_3 in equation (i) $-\frac{2}{3} \hat{j} + \frac{1}{3} \hat{k} + c_2 + \frac{1}{6} [\hat{j} + \hat{k}] = \hat{i}$

$\Rightarrow c_2 = \hat{i} - \frac{2}{3} \hat{j} + \frac{1}{3} \hat{k} + \frac{1}{6} \hat{j} + \frac{1}{6} \hat{k} = \hat{i} + \left(\frac{-4+1}{6} \right) \hat{j} + \left(\frac{2+1}{6} \right) \hat{k} = \hat{i} + \left(\frac{-3}{6} \right) \hat{j} + \left(\frac{3}{6} \right) \hat{k}$

$\Rightarrow c_2 = \hat{i} - \frac{1}{2} \hat{j} + \frac{1}{2} \hat{k}$

Using values of c_1, c_2 & c_3 in equation (i)

$\vec{v}(t) = \left(-\frac{2}{3} \hat{j} + \frac{1}{3} \hat{k} \right) e^{-t} + \left(\hat{i} - \frac{1}{2} \hat{j} + \frac{1}{2} \hat{k} \right) + \left(\frac{1}{6} \hat{j} + \frac{1}{6} \hat{k} \right) e^{2t}$

$\vec{v}(t) = \hat{i} + \left(-\frac{2}{3} e^{-t} - \frac{1}{2} + \frac{1}{6} e^{2t} \right) \hat{j} + \left(\frac{1}{3} e^{-t} + \frac{1}{2} + \frac{1}{6} e^{2t} \right) \hat{k}$

Q#10: Prove that (i) $\int \vec{a} \cdot \vec{f}(t) dt = \vec{a} \cdot \int \vec{f}(t) dt$ (ii) $\int \vec{a} \times \vec{f}(t) dt = \vec{a} \times \int \vec{f}(t) dt$

(i) $\int \vec{a} \cdot \vec{f}(t) dt = \vec{a} \cdot \int \vec{f}(t) dt$

Proof: Let

$$\begin{aligned} \frac{d}{dt} [\vec{a} \cdot \int \vec{f}(t) dt] &= \frac{d\vec{a}}{dt} \cdot \int \vec{f}(t) dt + \vec{a} \cdot \frac{d}{dt} [\int \vec{f}(t) dt] \\ &= (0) \cdot \int \vec{f}(t) dt + \vec{a} \cdot \frac{d}{dt} [\int \vec{f}(t) dt] \qquad \therefore \frac{d\vec{a}}{dt} = 0 \end{aligned}$$

$$\frac{d}{dt} [\vec{a} \cdot \int \vec{f}(t) dt] = \vec{a} \cdot \vec{f}(t)$$

$$d(\vec{a} \cdot \int \vec{f}(t) dt) = \vec{a} \cdot \vec{f}(t) dt$$

On integrating both sides

$$\int d(\vec{a} \cdot \int \vec{f}(t) dt) = \int \vec{a} \cdot \vec{f}(t) dt$$

$$\vec{a} \cdot \int \vec{f}(t) dt = \int \vec{a} \cdot \vec{f}(t) dt$$

Hence proved that

$$\int \vec{a} \cdot \vec{f}(t) dt = \vec{a} \cdot \int \vec{f}(t) dt$$

(ii) $\int \vec{a} \times \vec{f}(t) dt = \vec{a} \times \int \vec{f}(t) dt$

Proof: Let

$$\begin{aligned} \frac{d}{dt} [\vec{a} \times \int \vec{f}(t) dt] &= \frac{d\vec{a}}{dt} \times \int \vec{f}(t) dt + \vec{a} \times \frac{d}{dt} [\int \vec{f}(t) dt] \\ &= (0) \times \int \vec{f}(t) dt + \vec{a} \times \frac{d}{dt} [\int \vec{f}(t) dt] \qquad \therefore \frac{d\vec{a}}{dt} = 0 \end{aligned}$$

$$\frac{d}{dt} [\vec{a} \times \int \vec{f}(t) dt] = \vec{a} \times \vec{f}(t)$$

$$d(\vec{a} \times \int \vec{f}(t) dt) = \vec{a} \times \vec{f}(t) dt$$

On integrating both sides

$$\int d(\vec{a} \times \int \vec{f}(t) dt) = \int \vec{a} \times \vec{f}(t) dt$$

$$\vec{a} \times \int \vec{f}(t) dt = \int \vec{a} \times \vec{f}(t) dt$$

Hence proved that

$$\int \vec{a} \times \vec{f}(t) dt = \vec{a} \times \int \vec{f}(t) dt$$

Q#11: Evaluate $\int_2^3 \vec{r} \cdot \frac{d\vec{r}}{dt} dt$ **if** $\vec{r}(2) = 2\hat{i} - \hat{j} + 2\hat{k}$ **&** $\vec{r}(3) = 4\hat{i} - 2\hat{j} + 3\hat{k}$.

Solution: We know that $\vec{r} \cdot \frac{d\vec{r}}{dt} = r \frac{dr}{dt}$ **Then**

Let $I = \int_2^3 \vec{r} \cdot \frac{d\vec{r}}{dt} dt = \int_2^3 r \frac{dr}{dt} dt = \int_2^3 r dr = \left[\frac{r^2}{2} \right]_2^3 = \frac{1}{2} [r^2]_2^3 = \frac{1}{2} [r^2(3) - r^2(2)]$

$\Rightarrow I = \frac{1}{2} [|\vec{r}(3)|^2 - |\vec{r}(2)|^2]$ ----- (i)

Given that

$\vec{r}(2) = 2\hat{i} - \hat{j} + 2\hat{k}$ **&** $\vec{r}(3) = 4\hat{i} - 2\hat{j} + 3\hat{k}$

Then $|\vec{r}(2)|^2 = (2)^2 + (-1)^2 + (2)^2$ **&** $|\vec{r}(3)|^2 = (4)^2 + (-2)^2 + (3)^2$
 $= 4 + 1 + 4$ $= 16 + 4 + 9$

$|\vec{r}(2)|^2 = 9$ **&** $|\vec{r}(3)|^2 = 29$

Using values in equation (i)

$I = \frac{1}{2} [|\vec{r}(3)|^2 - |\vec{r}(2)|^2] = \frac{1}{2} [29 - 9] = \frac{1}{2} [20] = 10$

Hence $\int_2^3 \vec{r} \cdot \frac{d\vec{r}}{dt} dt = 10$

Q#12: Find $\vec{f}(t)$ **when** $\vec{f}'(t) = e^t \hat{i} + 2t\hat{j} - \sin t \hat{k}$ **and** $\vec{f}(0) = 2\hat{i} + 3\hat{j} + 4\hat{k}$.

Solution: Given $\vec{f}'(t) = e^t \hat{i} + 2t\hat{j} - \sin t \hat{k}$

On integrating both sides

$\vec{f}(t) = \int [e^t \hat{i} + 2t\hat{j} - \sin t \hat{k}] dt = \hat{i} \int e^t dt + \hat{j} [2 \int t dt] + \hat{k} [- \int \sin t dt]$
 $= \hat{i} [e^t] + \hat{j} \left[2 \left(\frac{t^2}{2} \right) \right] + \hat{k} [-(-\cos t)]$

$\vec{f}(t) = e^t \hat{i} + t^2 \hat{j} + \cos t \hat{k} + \vec{A}$ -----(i)

Given that $\vec{f}(0) = 2\hat{i} + 3\hat{j} + 4\hat{k}$

$2\hat{i} + 3\hat{j} + 4\hat{k} = e^0 \hat{i} + (0)^2 \hat{j} + \cos(0) \hat{k} + \vec{A}$

$2\hat{i} + 3\hat{j} + 4\hat{k} = 1\hat{i} + 0\hat{j} + 1\hat{k} + \vec{A} \Rightarrow \vec{A} = 2\hat{i} + 3\hat{j} + 4\hat{k} - \hat{i} - \hat{k} \Rightarrow \vec{A} = \hat{i} + 3\hat{j} + 3\hat{k}$

Using in equation (i) $\vec{f}(t) = e^t \hat{i} + t^2 \hat{j} + \cos t \hat{k} + \hat{i} + 3\hat{j} + 3\hat{k}$

$\vec{f}(t) = (1 + e^t) \hat{i} + (3 + t^2) \hat{j} + (3 + \cos t) \hat{k}$

Q#13: (a) If $\vec{f}(t) = (3t^2 - t)\hat{i} + (2 - 6t)\hat{j} - 4t\hat{k}$. Find (i) $\int \vec{f}(t) dt$ (ii) $\int_2^4 \vec{f}(t) dt$

(b) $\int_0^{\pi/2} [3 \sin t \hat{i} + 2 \cos t \hat{j}] dt$

(a) If $\vec{f}(t) = (3t^2 - t)\hat{i} + (2 - 6t)\hat{j} - 4t\hat{k}$. Find (i) $\int \vec{f}(t) dt$ (ii) $\int_2^4 \vec{f}(t) dt$

Solution: Given $\vec{f}(t) = (3t^2 - t)\hat{i} + (2 - 6t)\hat{j} - 4t\hat{k}$

(i) $\int \vec{f}(t) dt = \int [(3t^2 - t)\hat{i} + (2 - 6t)\hat{j} - 4t\hat{k}] dt$

$$= \hat{i} \int (3t^2 - t) dt + \hat{j} \int (2 - 6t) dt + \hat{k} \int [-4t] dt$$

$$= \hat{i} \left[\frac{3t^3}{3} - \frac{t^2}{2} \right] + \hat{j} \left[2t - \frac{6t^2}{2} \right] + \hat{k} \left[\frac{-4t^2}{2} \right]$$

$$\int \vec{f}(t) dt = \hat{i} \left[t^3 - \frac{t^2}{2} \right] + \hat{j} [2t - 3t^2] - 2\hat{k} [t^2] + c \quad \{c \text{ is constant of integration}\}$$

(ii) $\int_2^4 \vec{f}(t) dt = \hat{i} \left[t^3 - \frac{t^2}{2} \right]_2^4 + \hat{j} [2t - 3t^2]_2^4 - 2\hat{k} [t^2]_2^4$

$$= \hat{i} \left[\left(4^3 - \frac{4^2}{2} \right) - \left(2^3 - \frac{2^2}{2} \right) \right] + \hat{j} \left[\left(2\{4\} - \frac{6\{4\}^2}{2} \right) - \left(2\{2\} - \frac{6\{2\}^2}{2} \right) \right] - 2\hat{k} [4^2 - 2^2]$$

$$= \hat{i} [64 - 8 - 4 + 2] + \hat{j} [8 - 48 - 4 + 12] - 2\hat{k} [16 - 4]$$

$$\int_2^4 \vec{f}(t) dt = 54\hat{i} - 32\hat{j} - 24\hat{k}$$

(b) $\int_0^{\pi/2} [3 \sin t \hat{i} + 2 \cos t \hat{j}] dt$

Solution: Let $I = \int_0^{\pi/2} [3 \sin t \hat{i} + 2 \cos t \hat{j}] dt$

$$I = \hat{i} \left[3 \int_0^{\pi/2} \sin t dt \right] + \hat{j} \left[2 \int_0^{\pi/2} \cos t dt \right]$$

$$I = \hat{i} \left[3 \left(\frac{-\cos t}{2} \right) \right]_0^{\pi/2} + \hat{j} \left[2 \left(\frac{\sin t}{2} \right) \right]_0^{\pi/2}$$

$$I = \frac{-3}{2} \hat{i} [\cos t]_0^{\pi/2} + \hat{j} [\sin t]_0^{\pi/2}$$

$$I = \frac{-3}{2} \hat{i} \left[\cos \frac{\pi}{2} - \cos 0 \right] + \hat{j} \left[\sin \frac{\pi}{2} - \sin 0 \right]$$

$$I = \frac{-3}{2} \hat{i} [0 - 1] + \hat{j} [1 - 0]$$

$$I = \frac{3}{2} \hat{i} + \hat{j}$$

Q#15: Evaluate $\int_0^7 \vec{r} \cdot \frac{d\vec{r}}{dt} dt$ **if** $\vec{r}(0) = 5\hat{i} - 3\hat{j} + 2\hat{k}$ **&** $\vec{r}(7) = \hat{i} + 8\hat{j} + 9\hat{k}$.

Solution: We know that $\vec{r} \cdot \frac{d\vec{r}}{dt} = r \frac{dr}{dt}$ **Then**

$$I = \int_0^7 \vec{r} \cdot \frac{d\vec{r}}{dt} dt = \int_0^7 r \frac{dr}{dt} dt = \int_0^7 r dr = \left[\frac{r^2}{2} \right]_0^7 = \frac{1}{2} [r^2]_0^7 = \frac{1}{2} [r^2(7) - r^2(0)]$$

$$I = \frac{1}{2} [|\vec{r}(7)|^2 - |\vec{r}(0)|^2] \text{ ----- (i)}$$

Given that $\vec{r}(0) = 5\hat{i} - 3\hat{j} + 2\hat{k}$ **&** $\vec{r}(7) = \hat{i} + 8\hat{j} + 9\hat{k}$.

Then $|\vec{r}(0)|^2 = (5)^2 + (-3)^2 + (2)^2$ **&** $|\vec{r}(7)|^2 = (1)^2 + (8)^2 + (9)^2$

$$|\vec{r}(0)|^2 = 25 + 9 + 4 \quad \& \quad |\vec{r}(7)|^2 = 1 + 64 + 81$$

$$|\vec{r}(0)|^2 = 38 \quad \& \quad |\vec{r}(7)|^2 = 146$$

Using values in equation (i)

$$I = \frac{1}{2} [|\vec{r}(7)|^2 - |\vec{r}(0)|^2] = \frac{1}{2} [146 - 38] = \frac{1}{2} [108] = 54$$

Hence $\int_2^3 \vec{r} \cdot \frac{d\vec{r}}{dt} dt = 54$

Q#16: Example#05:If $\vec{r} = 5t^2\hat{i} + t\hat{j} - t^3\hat{k}$ **. Prove that** $\int_1^2 (\vec{r} \times \frac{d^2\vec{r}}{dt^2}) dt = -14\hat{i} + 75\hat{j} - 15\hat{k}$

Solution: Given vector $\vec{r} = 5t^2\hat{i} + t\hat{j} - t^3\hat{k}$ **Then** $\frac{d\vec{r}}{dt} = 10t\hat{i} + \hat{j} - 3t^2\hat{k}$ **&** $\frac{d^2\vec{r}}{dt^2} = 10\hat{i} + 0\hat{j} - 6t\hat{k}$

Now $\vec{r} \times \frac{d^2\vec{r}}{dt^2} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 5t^2 & t & -t^3 \\ 10 & 0 & -6t \end{vmatrix} = \hat{i} \begin{vmatrix} t & -t^3 \\ 0 & -6t \end{vmatrix} - \hat{j} \begin{vmatrix} 5t^2 & -t^3 \\ 10 & -6t \end{vmatrix} + \hat{k} \begin{vmatrix} 5t^2 & t \\ 10 & 0 \end{vmatrix}$

$$= [-6t^2 - 0]\hat{i} - [-30t^3 + 10t^3]\hat{j} + [0 - 10t]\hat{k} = -6t^2\hat{i} - [-20t^3]\hat{j} + [-10t]\hat{k}$$

$$\vec{r} \times \frac{d^2\vec{r}}{dt^2} = -6t^2\hat{i} + 20t^3\hat{j} - 10t\hat{k}$$

On Integrating $\int (\vec{r} \times \frac{d^2\vec{r}}{dt^2}) dt = \int [-6t^2\hat{i} + 20t^3\hat{j} - 10t\hat{k}] dt = \hat{i}[-6 \int t^2 dt] + \hat{j}[20 \int t^3 dt] + \hat{k}[-10 \int t dt]$

$$\int (\vec{r} \times \frac{d^2\vec{r}}{dt^2}) dt = \hat{i} \left[-6 \left(\frac{t^3}{3} \right) \right] + \hat{j} \left[20 \left(\frac{t^4}{4} \right) \right] + \hat{k} \left[-10 \left(\frac{t^2}{2} \right) \right] = \hat{i}[-2t^3] + \hat{j}[5t^4] + \hat{k}[-5t^2]$$

Now $\int_1^2 (\vec{r} \times \frac{d^2\vec{r}}{dt^2}) dt = -2\hat{i} [t^3]_1^2 + 5\hat{j} [t^4]_1^2 - 5\hat{k} [t^2]_1^2 = -2\hat{i} [2^3 - 1^3] + 5\hat{j} [2^4 - 1^4] - 5\hat{k} [2^2 - 1^2]$

$$= -2\hat{i} [8 - 1] + 5\hat{j} [16 - 1] - 5\hat{k} [4 - 1] = -2\hat{i} [7] + 5\hat{j} [15] - 5\hat{k} [3]$$

$$\int_1^2 (\vec{r} \times \frac{d^2\vec{r}}{dt^2}) dt = -14\hat{i} + 75\hat{j} - 15\hat{k} \quad \text{Hence proved.}$$

Q#17: If $\vec{f} = \hat{i} - 3\hat{j} + 2t\hat{k}$; $\vec{g} = t\hat{i} - 2\hat{j} + 2\hat{k}$ & $\vec{h} = 3\hat{i} + t\hat{j} - \hat{k}$. Prove that $\int_1^2 \vec{f} \cdot (\vec{g} \times \vec{h}) dt = 1$

Solution: Given vectors $\vec{f} = \hat{i} - 3\hat{j} + 2t\hat{k}$; $\vec{g} = t\hat{i} - 2\hat{j} + 2\hat{k}$ & $\vec{h} = 3\hat{i} + t\hat{j} - \hat{k}$

Then
$$\vec{f} \cdot (\vec{g} \times \vec{h}) = \begin{vmatrix} 1 & -3 & 2t \\ t & -2 & 2 \\ 3 & t & -1 \end{vmatrix} = t \begin{vmatrix} -2 & 2 \\ t & -1 \end{vmatrix} - (-3) \begin{vmatrix} t & 2 \\ 3 & -1 \end{vmatrix} + 2t \begin{vmatrix} t & -2 \\ 3 & t \end{vmatrix}$$

$$= 1 [(-2)(-1) - (t)(2)] + 3 [(t)(-1) - (3)(2)] + 2t [(t)(t) - (3)(-2)]$$

$$= 1 [2 - 2t] + 3 [-t - 6] + 2t [t^2 + 6] = 2 - 2t - 3t - 18 + 2t^3 + 12t$$

$$\vec{f} \cdot (\vec{g} \times \vec{h}) = 2t^3 + 7t - 17$$

Now
$$I = \int_1^2 \vec{f} \cdot (\vec{g} \times \vec{h}) dt = \int_1^2 [2t^3 + 7t - 17] dt = \left[2 \left(\frac{t^4}{4} \right) + 7 \left(\frac{t^2}{2} \right) - 17t \right]_1^2 = \left[\frac{t^4}{2} + \frac{7t^2}{2} - 17t \right]_1^2$$

$$I = \left[\frac{t^4 + 7t^2 - 34t}{2} \right]_1^2 = \left[\frac{2^4 + 7(2)^2 - 34(2)}{2} - \frac{1^4 + 7(1)^2 - 34(1)}{2} \right] = \left[\frac{16 + 28 - 68}{2} - \frac{1 + 7 - 34}{2} \right]$$

$$I = \left[\frac{-24}{2} - \frac{-26}{2} \right] = \left[\frac{-24}{2} + \frac{26}{2} \right] = \left[\frac{-24 + 26}{2} \right] = \frac{2}{2} = 1$$

Hence proved that

$$\int_1^2 \vec{f} \cdot (\vec{g} \times \vec{h}) dt = 1$$

Q# 18: Evaluate $\int_1^7 \vec{r} \cdot \frac{d\vec{r}}{dt} dt$ if $\vec{r}(1) = 5\hat{i} - 3\hat{j} + 2\hat{k}$ & $\vec{r}(7) = \hat{i} + 8\hat{j} + 9\hat{k}$.

Solution: We know that $\vec{r} \cdot \frac{d\vec{r}}{dt} = r \frac{dr}{dt}$ **Then**

$$I = \int_1^7 \vec{r} \cdot \frac{d\vec{r}}{dt} dt = \int_1^7 r \frac{dr}{dt} dt = \int_1^7 r dr = \left[\frac{r^2}{2} \right]_1^7 = \frac{1}{2} [r^2]_1^7 = \frac{1}{2} [r^2(7) - r^2(1)]$$

$$I = \frac{1}{2} [|\vec{r}(7)|^2 - |\vec{r}(1)|^2] \text{ ----- (i)}$$

Given that $\vec{r}(1) = 5\hat{i} - 3\hat{j} + 2\hat{k}$ & $\vec{r}(7) = \hat{i} + 8\hat{j} + 9\hat{k}$.

Then $|\vec{r}(1)|^2 = (5)^2 + (-3)^2 + (2)^2$ & $|\vec{r}(7)|^2 = (1)^2 + (8)^2 + (9)^2$

$$|\vec{r}(1)|^2 = 25 + 9 + 4$$
 & $|\vec{r}(7)|^2 = 1 + 64 + 81$

$$|\vec{r}(1)|^2 = 38$$
 & $|\vec{r}(7)|^2 = 146$

Using values in equation (i)

$$I = \frac{1}{2} [|\vec{r}(7)|^2 - |\vec{r}(1)|^2] = \frac{1}{2} [146 - 38] = \frac{1}{2} [108] = 54$$

Hence $\int_1^7 \vec{r} \cdot \frac{d\vec{r}}{dt} dt = 54$

Q# 19: (i) Example#04: Integrate the equation $\frac{d^2\vec{r}}{dt^2} = -n^2 \vec{r}$.

Solution : Given equation is

$$\frac{d^2\vec{r}}{dt^2} = -n^2 \vec{r}$$

Multiplying both sides of equation by $\left(\frac{d\vec{r}}{dt}\right)$:

$$\left(\frac{d\vec{r}}{dt}\right) \frac{d^2\vec{r}}{dt^2} = -n^2 \vec{r} \left(\frac{d\vec{r}}{dt}\right)$$

On integrating both sides $\int \left(\frac{d\vec{r}}{dt}\right)^1 \left(\frac{d^2\vec{r}}{dt^2}\right) dt = -n^2 \int \vec{r} \left(\frac{d\vec{r}}{dt}\right) dt$

{Power rule of integration}

$$\frac{\left(\frac{d\vec{r}}{dt}\right)^{1+1}}{1+1} = -n^2 \frac{\vec{r}^{1+1}}{1+1} + A$$

$$\frac{\left(\frac{d\vec{r}}{dt}\right)^2}{2} = -n^2 \frac{\vec{r}^2}{2} + A$$

Multiplying both sides by 2

$$\left(\frac{d\vec{r}}{dt}\right)^2 = -n^2 \vec{r}^2 + 2A$$

$$\left(\frac{d\vec{r}}{dt}\right)^2 = -n^2 \vec{r}^2 + c \quad \therefore 2A = c$$

Q# 19: (ii) If $\frac{d^2\vec{r}}{dt^2} = -\mu \vec{r}$. **then show that** $\left(\frac{d\vec{r}}{dt}\right)^2 = -\mu \vec{r}^2 + c$ where c is constant.

Solution : Given equation is $\frac{d^2\vec{r}}{dt^2} = -\mu \vec{r}$

Multiplying both sides of equation by $\left(\frac{d\vec{r}}{dt}\right)$:

$$\left(\frac{d\vec{r}}{dt}\right) \frac{d^2\vec{r}}{dt^2} = -\mu \vec{r} \left(\frac{d\vec{r}}{dt}\right)$$

On integrating both sides $\int \left(\frac{d\vec{r}}{dt}\right)^1 \left(\frac{d^2\vec{r}}{dt^2}\right) dt = -\mu \int \vec{r} \left(\frac{d\vec{r}}{dt}\right) dt$

{Power rule of integration}

$$\frac{\left(\frac{d\vec{r}}{dt}\right)^{1+1}}{1+1} = -\mu \frac{\vec{r}^{1+1}}{1+1} + A$$

$$\frac{\left(\frac{d\vec{r}}{dt}\right)^2}{2} = -\mu \frac{\vec{r}^2}{2} + A$$

Multiplying both sides by 2

$$\left(\frac{d\vec{r}}{dt}\right)^2 = -\mu \vec{r}^2 + 2A$$

Hence proved

$$\left(\frac{d\vec{r}}{dt}\right)^2 = -\mu \vec{r}^2 + c \quad \therefore 2A = c$$

Q#20: If $\frac{d^2\vec{r}}{dt^2} = 6t\hat{i} - 24t^2\hat{j} + 4\sin t\hat{k}$. Find $\vec{r}(t)$, when $t = 0$, $\vec{r} = 2\hat{i} + \hat{j}$ and $\frac{d\vec{r}}{dt} = -\hat{i} - 3\hat{k}$

Solution: Given equation $\frac{d^2\vec{r}}{dt^2} = 6t\hat{i} - 24t^2\hat{j} + 4\sin t\hat{k}$

On integrating both sides

$$\begin{aligned} \frac{d\vec{r}}{dt} &= \int [6t\hat{i} - 24t^2\hat{j} + 4\sin t\hat{k}] dt \\ &= \hat{i}[6\int t dt] + \hat{j}[-24\int t^2 dt] + \hat{k}[4\int \sin t dt] \\ &= \hat{i}\left[6\left(\frac{t^2}{2}\right)\right] + \hat{j}\left[-24\left(\frac{t^3}{3}\right)\right] + \hat{k}[4(-\cos t)] + \vec{A} \\ &= \hat{i}[3t^2] + \hat{j}[-8t^3] + \hat{k}[-4\cos t] + \vec{A} \end{aligned}$$

$$\frac{d\vec{r}}{dt} = 3t^2\hat{i} - 8t^3\hat{j} - 4\cos t\hat{k} + \vec{A} \text{-----(i)}$$

When $t=0$ & $\frac{d\vec{r}}{dt} = -\hat{i} - 3\hat{k}$ then $3(0)^2\hat{i} - 8(0)^3\hat{j} - 4\cos(0)\hat{k} + \vec{A} = -\hat{i} - 3\hat{k}$

$$0\hat{i} + 0\hat{j} - 4\hat{k} + \vec{A} = -\hat{i} - 3\hat{k} \Rightarrow \vec{A} = -\hat{i} - 3\hat{k} + 4\hat{k} \Rightarrow \vec{A} = -\hat{i} + \hat{k}$$

Using in equation (i) $\frac{d\vec{r}}{dt} = 3t^2\hat{i} - 8t^3\hat{j} - 4\cos t\hat{k} + -\hat{i} + \hat{k}$

$$\frac{d\vec{r}}{dt} = (3t^2 - 1)\hat{i} - 8t^3\hat{j} + (1 - 4\cos t)\hat{k}$$

On integrating both sides

$$\begin{aligned} \vec{r} &= \int [(3t^2 - 1)\hat{i} - 8t^3\hat{j} + (1 - 4\cos t)\hat{k}] dt \\ &= \hat{i}[\int (3t^2 - 1) dt] + \hat{j}[-8\int t^3 dt] + \hat{k}[\int (1 - 4\cos t) dt] \\ &= \hat{i}\left[3\left(\frac{t^3}{3}\right) - t\right] + \hat{j}\left[-8\left(\frac{t^4}{4}\right)\right] + \hat{k}[(t - 4\sin t)] + \vec{B} \end{aligned}$$

$$\vec{r} = \hat{i}[t^3 - t] + \hat{j}[-2t^4] + \hat{k}[t - 4\sin t] + \vec{A}$$

$$\vec{r} = [t^3 - t]\hat{i} - 2t^4\hat{j} + [t - 4\sin t]\hat{k} + \vec{B} \text{-----(ii)}$$

When $t=0$ & $\vec{r} = 2\hat{i} + \hat{j}$ then $[(0)^3 - (0)]\hat{i} - 2(0)^4\hat{j} + [(0) - 4\sin(0)]\hat{k} + \vec{B} = 2\hat{i} + \hat{j}$

$$\Rightarrow 0\hat{i} + 0\hat{j} + 0\hat{k} + \vec{B} = 2\hat{i} + \hat{j} \Rightarrow \vec{B} = 2\hat{i} + \hat{j}$$

Using in equation (ii)

$$\vec{r} = [t^3 - t]\hat{i} - 2t^4\hat{j} + [t - 4\sin t]\hat{k} + 2\hat{i} + \hat{j}$$

$$\vec{r} = [t^3 - t + 2]\hat{i} + (1 - 2t^4)\hat{j} + [t - 4\sin t]\hat{k}$$

Q#21: If $\vec{a} = t\hat{i} - 3\hat{j} + 2t\hat{k}$: $\vec{b} = \hat{i} - 2\hat{j} + 2\hat{k}$ & $\vec{c} = 3\hat{i} + t\hat{j} - \hat{k}$. Find $\int_1^2 \vec{f} \times (\vec{g} \times \vec{h}) dt$

Solution: Given vectors

$$\vec{a} = t\hat{i} - 3\hat{j} + 2t\hat{k} \quad ; \quad \vec{b} = \hat{i} - 2\hat{j} + 2\hat{k} \quad \& \quad \vec{c} = 3\hat{i} + t\hat{j} - \hat{k}$$

$$\vec{a} \times (\vec{b} \times \vec{c}) = (\vec{a} \cdot \vec{c})\vec{b} - (\vec{a} \cdot \vec{b})\vec{c}$$

$$= [(t\hat{i} - 3\hat{j} + 2t\hat{k}) \cdot (3\hat{i} + t\hat{j} - \hat{k})]\vec{b} - [(t\hat{i} - 3\hat{j} + 2t\hat{k}) \cdot (\hat{i} - 2\hat{j} + 2\hat{k})]\vec{c}$$

$$= \{3t - 3t - 2t\}\vec{b} - \{t + 6 + 4t\}\vec{c}$$

$$= (-2t)(\hat{i} - 2\hat{j} + 2\hat{k}) - (6+5t)(3\hat{i} + t\hat{j} - \hat{k})$$

$$= (-2t)\hat{i} + (4t)\hat{j} + (-4t)\hat{k} - 3(6 + 5t)\hat{i} - t(6 + 5t)\hat{j} + (6 + 5t)\hat{k}$$

$$= (-2t - 18 - 15t)\hat{i} + (4t - 6t - 5t^2)\hat{j} + (-4t + 6 + 5t)\hat{k}$$

$$= (-17t - 18)\hat{i} + (-5t^2 - 2t)\hat{j} + (t + 6)\hat{k}$$

$$\vec{a} \times (\vec{b} \times \vec{c}) = -(17t + 18)\hat{i} - (5t^2 + 2t)\hat{j} + (7t + 6)\hat{k}$$

Now

$$I = \int_1^2 \vec{a} \times (\vec{b} \times \vec{c}) dt = \int_1^2 [-(17t + 18)\hat{i} - (5t^2 + 2t)\hat{j} + (7t + 6)\hat{k}] dt$$

$$= [-\hat{i} \int (17t + 18) dt] - \hat{j} \int (5t^2 + 2t) dt + \hat{k} \int (7t + 6) dt]$$

$$= -\hat{i} \left[17 \left(\frac{t^2}{2} \right) + 18t \right]_1^2 - \hat{j} \left[5 \left(\frac{t^3}{3} \right) + 2 \left(\frac{t^2}{2} \right) \right]_1^2 + \hat{k} \left[7 \left(\frac{t^2}{2} \right) + 6t \right]_1^2$$

$$= -\hat{i} \left[\left\{ 17 \left(\frac{2^2}{2} \right) + 18(2) \right\} - \left\{ 17 \left(\frac{1^2}{2} \right) + 18(1) \right\} \right] - \hat{j} \left[\left\{ 5 \left(\frac{2^3}{3} \right) + 2 \left(\frac{2^2}{2} \right) \right\} - \left\{ 5 \left(\frac{1^3}{3} \right) + 2 \left(\frac{1^2}{2} \right) \right\} \right]$$

$$- \hat{k} \left[\left\{ \left(\frac{2^2}{2} \right) + 6(2) \right\} - \left\{ \left(\frac{1^2}{2} \right) + 6(1) \right\} \right]$$

$$= -\hat{i} \left[34 + 36 - \frac{17}{2} - 18 \right] - \hat{j} \left[\frac{40}{3} + 4 - \frac{5}{3} - 1 \right] + \hat{k} \left[2 + 12 - \frac{7}{2} - 6 \right]$$

$$= -\hat{i} \left[52 - \frac{17}{2} \right] - \hat{j} \left[\frac{40}{3} - \frac{5}{3} - 3 \right] + \left[8 - \frac{1}{2} \right] \hat{k}$$

$$= -\hat{i} \left[\frac{104-17}{2} \right] - \hat{j} \left[\frac{40-5-9}{3} \right] + \left[\frac{16-1}{2} \right] \hat{k}$$

$$= -\hat{i} \left[\frac{87}{2} \right] - \hat{j} \left[\frac{44}{3} \right] + \left[\frac{15}{2} \right] \hat{k}$$

$$I = -\frac{87}{2} \hat{i} - \frac{44}{3} \hat{j} + \frac{15}{2} \hat{k}$$

Q#22: The acceleration of a particle at any time t is given by $\vec{a} = 12 \cos 2t \hat{i} - 8 \sin 2t \hat{j} + 6t \hat{k}$. If velocity \vec{v} & Displacement \vec{r} are zero at $t=0$. then find \vec{v} & \vec{r} at any time.

Solution: Given that $\vec{a} = \frac{d\vec{v}}{dt} = 12 \cos 2t \hat{i} - 8 \sin 2t \hat{j} + 6t \hat{k}$

On integrating both sides

$$\begin{aligned} \vec{v} &= \int [12 \cos 2t \hat{i} - 8 \sin 2t \hat{j} + 6t \hat{k}] dt \\ &= \hat{i} [12 \int \cos 2t dt] + \hat{j} [-8 \int \sin 2t dt] + \hat{k} [6 \int t dt] \\ &= \hat{i} \left[12 \left(\frac{\sin 2t}{2} \right) \right] + \hat{j} \left[-8 \left(\frac{-\cos 2t}{2} \right) \right] + \hat{k} \left[6 \left(\frac{t^2}{2} \right) \right] + \vec{A} \\ \vec{v} &= 6 \sin 2t \hat{i} + 4 \cos 2t \hat{j} + 3t^2 \hat{k} + \vec{A} \text{-----(i)} \end{aligned}$$

When $t = 0$ & $\vec{v} = 0$ then

$$\begin{aligned} 6 \sin 2(0) \hat{i} + 4 \cos 2(0) \hat{j} + 3(0)^2 \hat{k} + \vec{A} &= 0 \\ 0 \hat{i} + 4 \hat{j} + 0 \hat{k} + \vec{A} &= 0 \implies \vec{A} = -4 \hat{j} \end{aligned}$$

Using in equation (i) $\vec{v} = 6 \sin 2t \hat{i} + 4 \cos 2t \hat{j} + 3t^2 \hat{k} - 4 \hat{j}$

$$\vec{v} = \frac{d\vec{r}}{dt} = 6 \sin 2t \hat{i} + (4 \cos 2t - 4) \hat{j} + 3t^2 \hat{k}$$

On integrating both sides

$$\begin{aligned} \vec{r} &= \int [6 \sin 2t \hat{i} + (4 \cos 2t - 4) \hat{j} + 3t^2 \hat{k}] dt \\ &= \hat{i} [6 \int \sin 2t dt] + \hat{j} [\int (4 \cos 2t - 4) dt] + \hat{k} [3 \int t^2 dt] \\ &= \hat{i} \left[6 \left(\frac{-\cos 2t}{2} \right) \right] + \hat{j} \left[4 \left(\frac{\sin 2t}{2} \right) - 4t \right] + 3 \hat{k} \left[\frac{t^3}{3} \right] + \vec{B} \\ \vec{r} &= -3 \cos 2t \hat{i} + [2 \sin 2t - 4t] \hat{j} + t^3 \hat{k} + \vec{B} \text{-----(ii)} \end{aligned}$$

When $t = 0$ & $\vec{r} = 0$ then

$$\begin{aligned} -3 \cos 2(0) \hat{i} + [2 \sin 2(0) - 4(0)] \hat{j} + (0)^3 \hat{k} + \vec{B} &= 0 \\ -3 \hat{i} + 0 \hat{j} + 0 \hat{k} + \vec{B} &= 0 \implies \vec{B} = 3 \hat{i} \end{aligned}$$

Using in equation (ii)

$$\begin{aligned} \vec{r} &= -3 \cos 2t \hat{i} + [2 \sin 2t - 4t] \hat{j} + t^3 \hat{k} + 3 \hat{i} \\ \vec{r} &= 3(1 - \cos 2t) \hat{i} + 2(\sin 2t - 2t) \hat{j} + t^3 \hat{k} \end{aligned}$$

The end of chapter #3